



## Answers

$$L_{RA} = 2000 \text{ m}$$

$$L_{AB} = 1000 \text{ m}$$

$$L_{AC} = 1500$$

$$D_{RA} = 450 \text{ mm}$$

$$D_{AB} = 350 \text{ mm}$$

$$D_{AC} = 400 \text{ mm}$$

rod  
members

$$Q_{AB} = 50 \text{ l/s}$$

$$Q_{AC} = 80 \text{ l/s}$$

$$Z_A = 49 \text{ m}$$

$$Z_B = 50$$

$$Z_C = 45 \text{ m}$$

$$Z_R = 22.2$$

$$\left. \begin{array}{l} \frac{P_B}{\gamma} \geq 20 \text{ m} \\ \frac{P_C}{\gamma} \geq 25 \text{ m} \end{array} \right\}$$

$$\frac{P_C}{\gamma} \geq 25 \text{ m}$$

1) along or A.  
2) stability analysis or A.



# $\Delta$ losses in pipes

1  $\Sigma$ otw  $\frac{P_B}{\rho g} = 20 \text{ m.}$

ADE:  $A \rightarrow B$   
 $H_A = H_B + \Sigma h_{A \rightarrow B}$

$$\frac{P_A}{\rho g} + z_A + \frac{V_A^2}{2g} = \frac{P_B}{\rho g} + z_B + \frac{V_B^2}{2g} + \Sigma h_{A \rightarrow B}$$

$$\frac{P_A}{\rho g} + z_A = 20 + 4 \text{ m} + \frac{8 f L}{g \pi^2 D^5} Q_{AB}^2$$

$$Q_{AB} = 0.050 \text{ m}^3/\text{s}$$

$$V = \frac{4Q}{\pi D^2} =$$

$$Re = \frac{V \cdot D}{\nu} =$$

24

$$f =$$

②

$$\sum \sigma_{\text{ow}} \quad \frac{p_c}{\rho g} = \cancel{2.5} \quad 2.5 \text{ m}$$

ADE A → C

$$H_A = H_C + s h_{A \rightarrow C}$$

$$\frac{p_A}{\rho g} + z_A + \frac{V_A^2}{2g} = \frac{p_C}{\rho g} + z_C + \frac{V_C^2}{2g} + s h_{A \rightarrow C}$$

$$\frac{p_A}{\rho g} + z_A = 2.5 + s h_{A \rightarrow C}$$

$$Q = 0.080 \text{ m}^3/\text{s}$$

$$V = \frac{4Q}{\pi D^2}$$

$$Re = \frac{VD}{\nu}$$

$$\frac{k}{D} = \frac{1}{400}$$

f =

# Επίλυση στο Συμπιεστότερο.

$$\frac{P_A}{\rho g} = \max \left\{ \begin{array}{l} \text{από την} \\ \text{εάνδυση} \end{array} , \begin{array}{l} \text{δευτερο} \\ \text{εάνδυση} \end{array} \right\}$$

ADE.

$R \rightarrow A.$  στο πιο συμπιεστό (μεγαλύτερη ζήνη)

$$Z_R = \left\{ \left( Z_A + \frac{P_A}{\rho g} \right) + \frac{V_A^2}{2g} \right\} + \delta h f_{R \rightarrow A}$$

$$Q_0 = Q_{AD} + Q_{AC} = \cancel{Q_0} = 0,130 \text{ m}^3/\text{s}$$

$$V = \frac{4 Q_0}{\pi D^2} \rightarrow f = \nu$$

$$h_{f_{R \rightarrow A}} = \frac{\delta f Q_0^2}{\pi D^5}$$

$$\rightarrow Z_R = \delta \nu$$