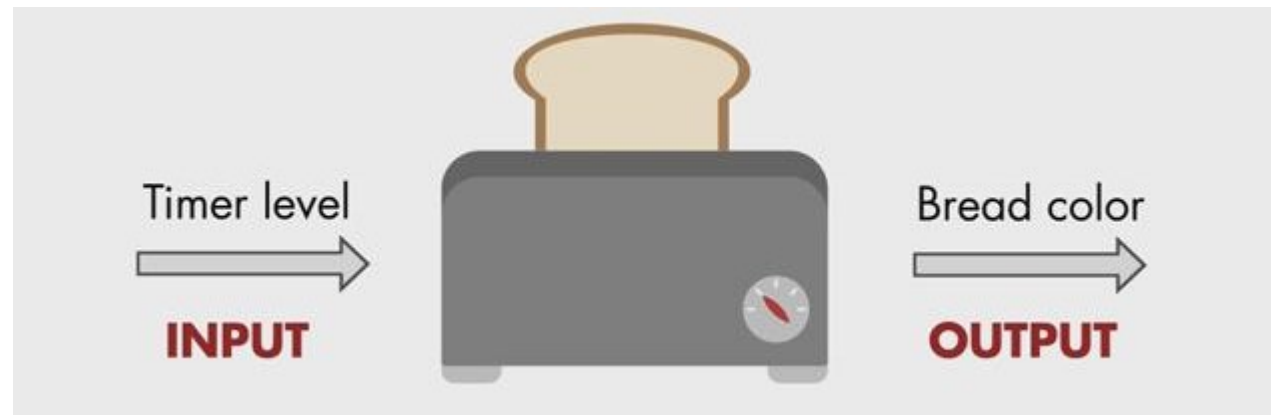


Robust Mechatronics

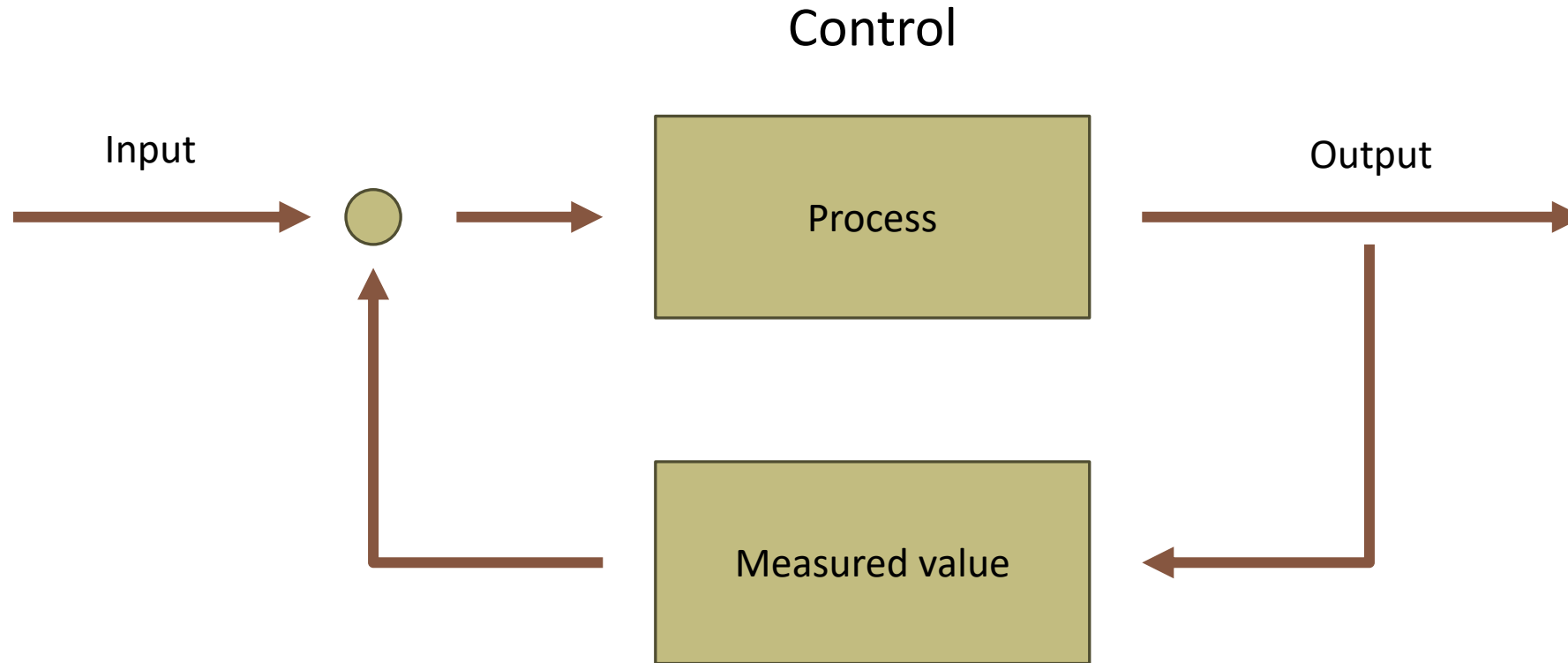
Mechatronics Automation



Dr Loukas Bampis, Assistant Professor
Mechatronics & Systems Automation Lab

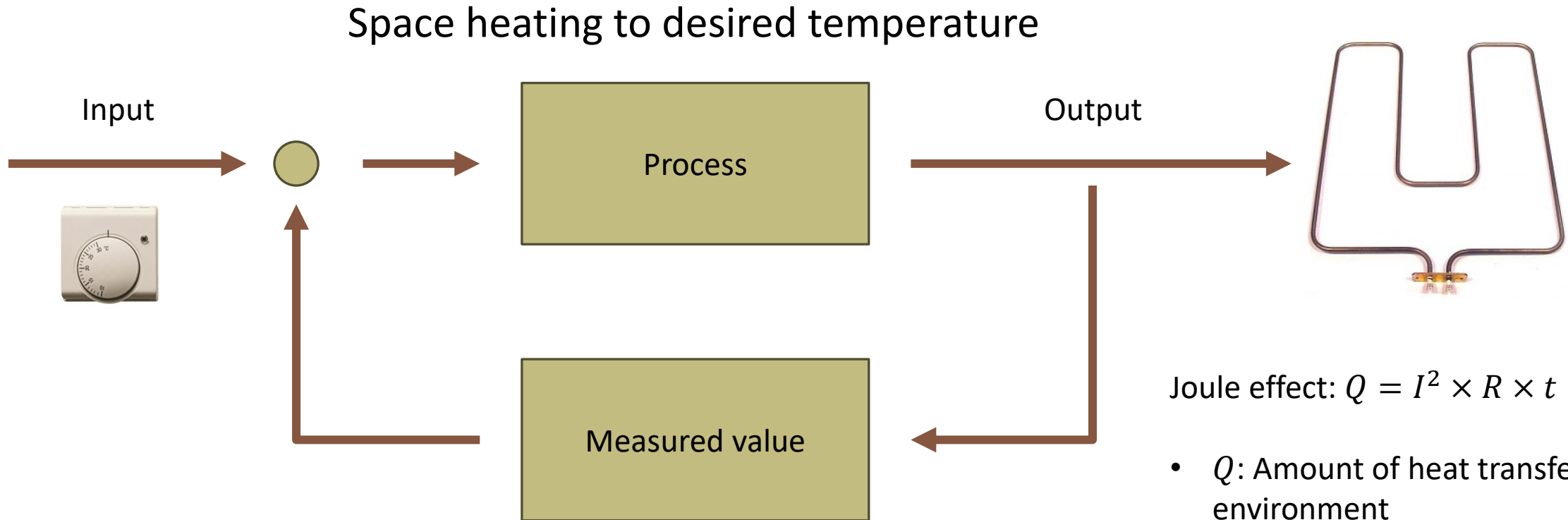
Mechatronics Automation

Automation system



Mechatronics Automation

Automation system



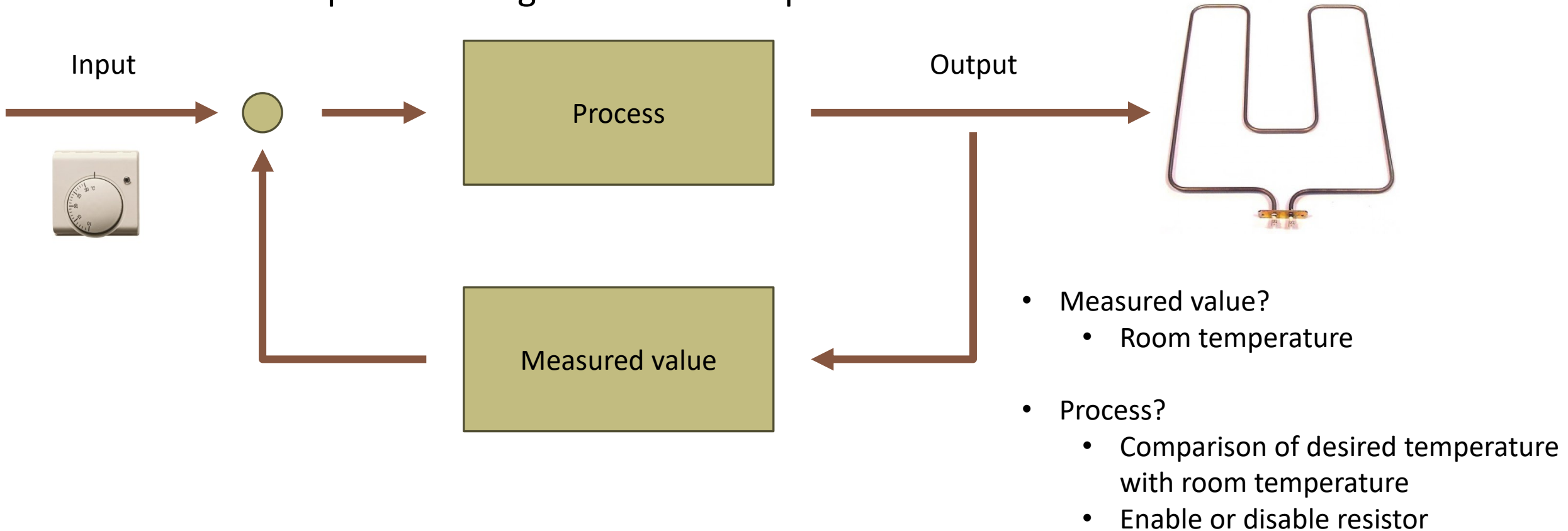
Joule effect: $Q = I^2 \times R \times t$

- Q : Amount of heat transferred to the environment
- I : Current
- R : Resistance
- t : Current transit time

Mechatronics Automation

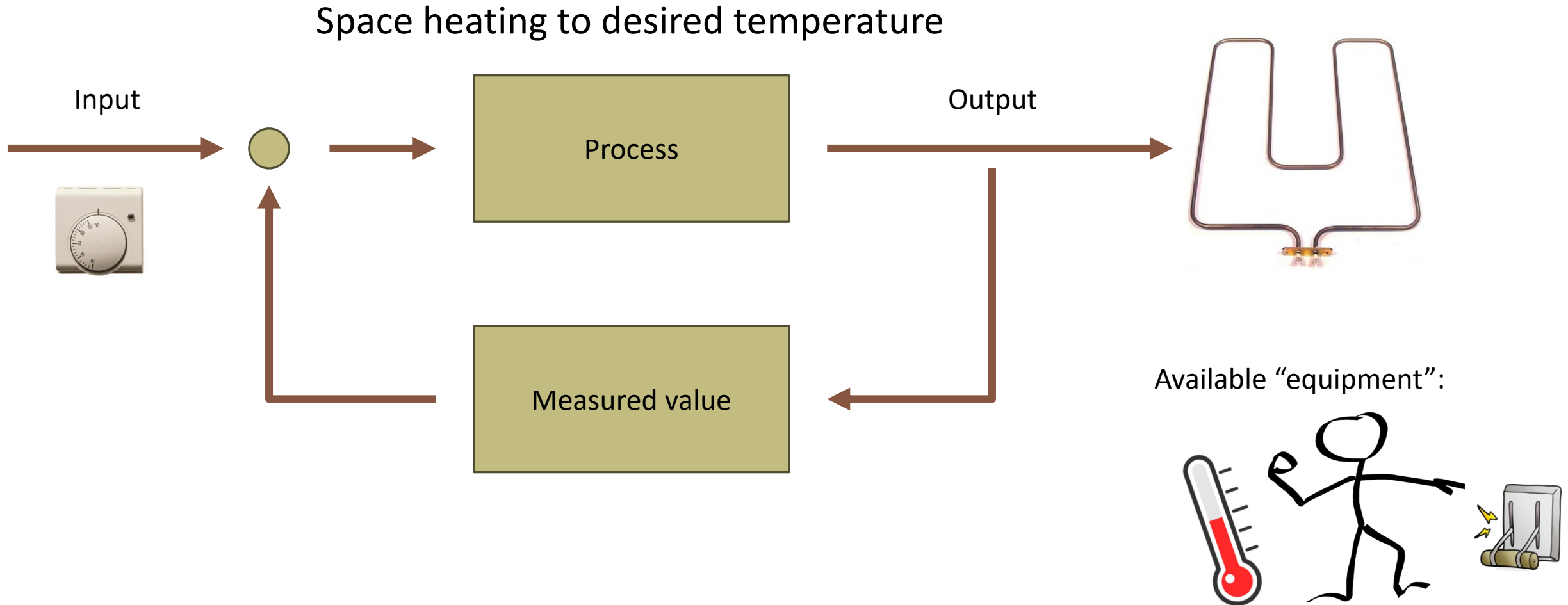
Automation system

Space heating to desired temperature



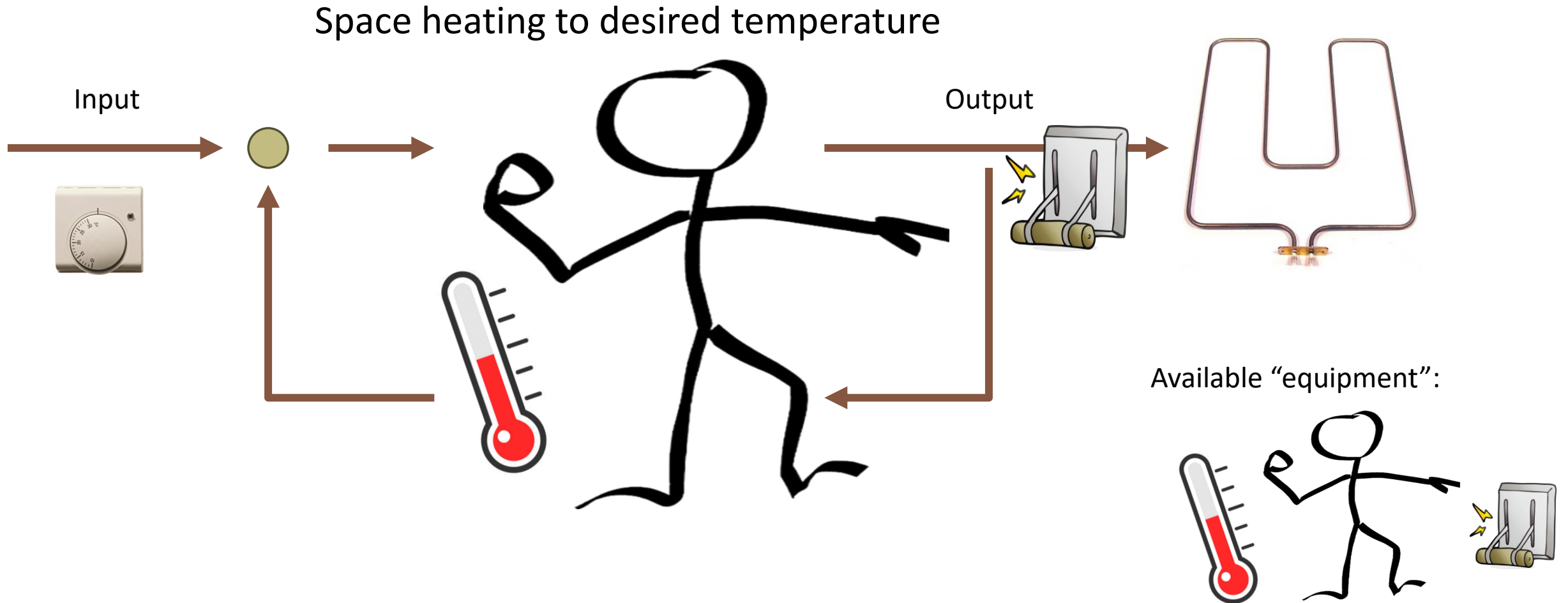
Mechatronics Automation

Automation system



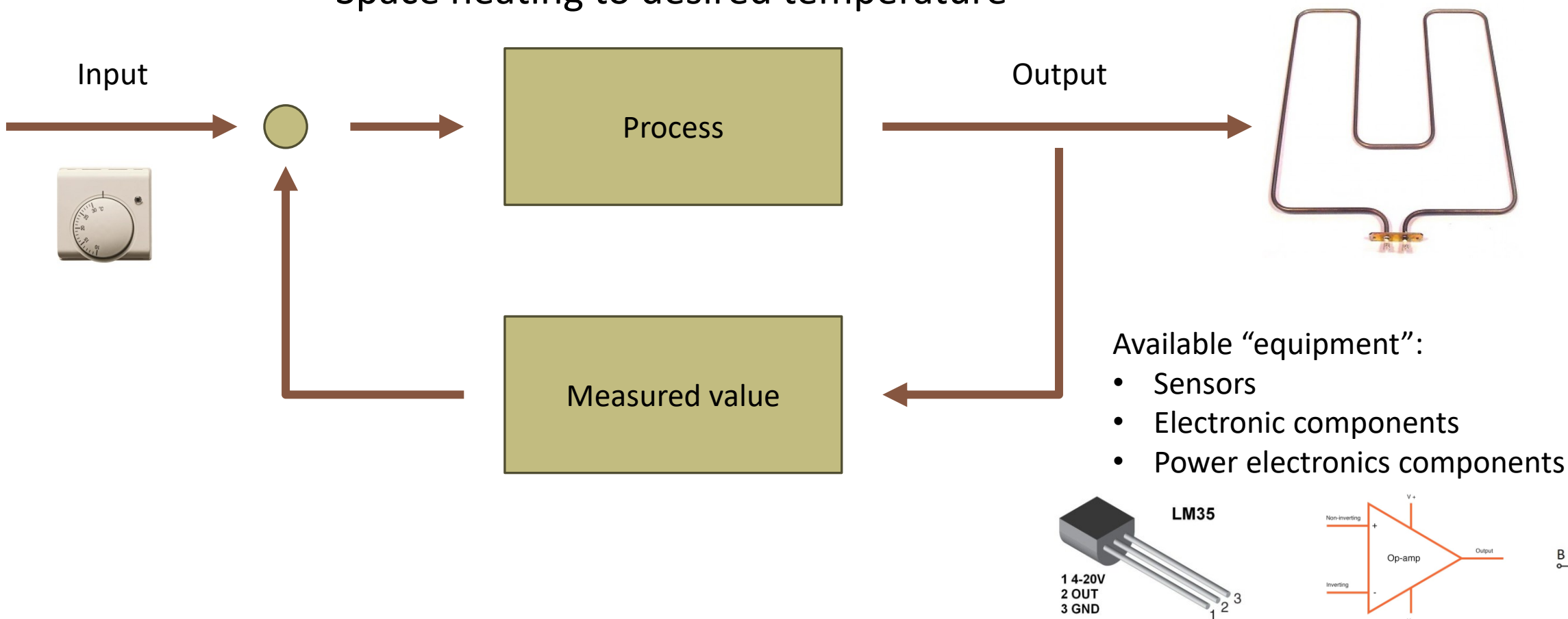
Mechatronics Automation

Automation system



Information system

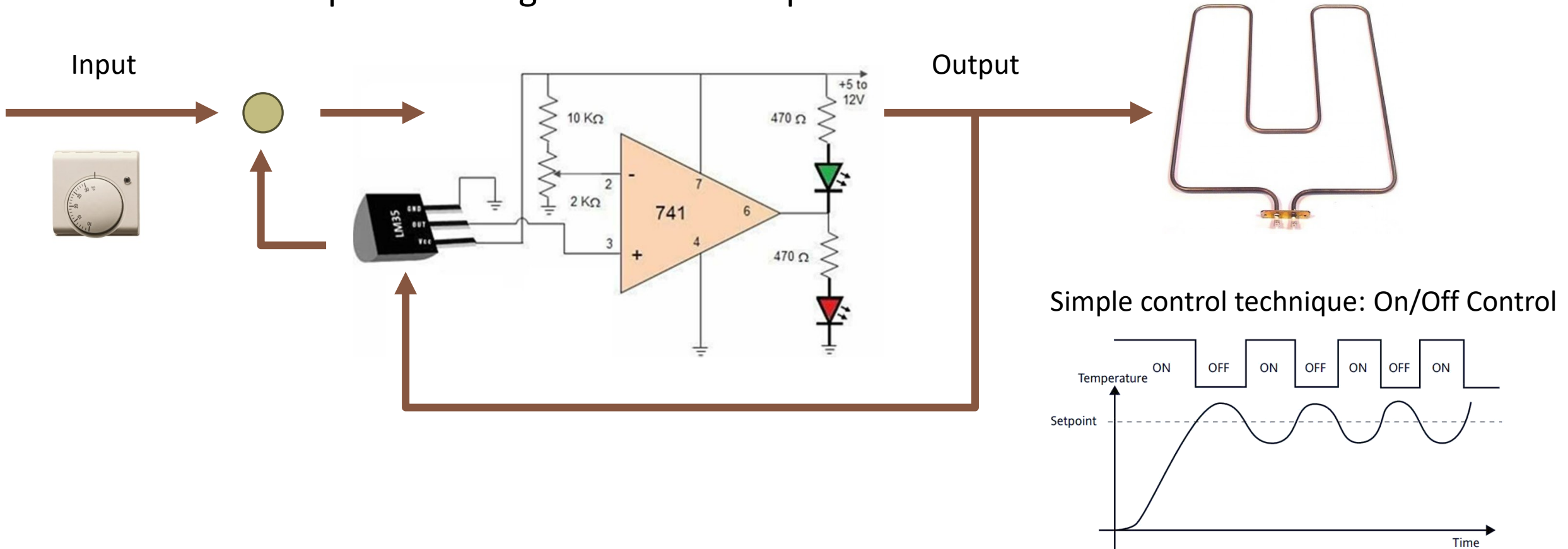
Space heating to desired temperature



Mechatronics Automation

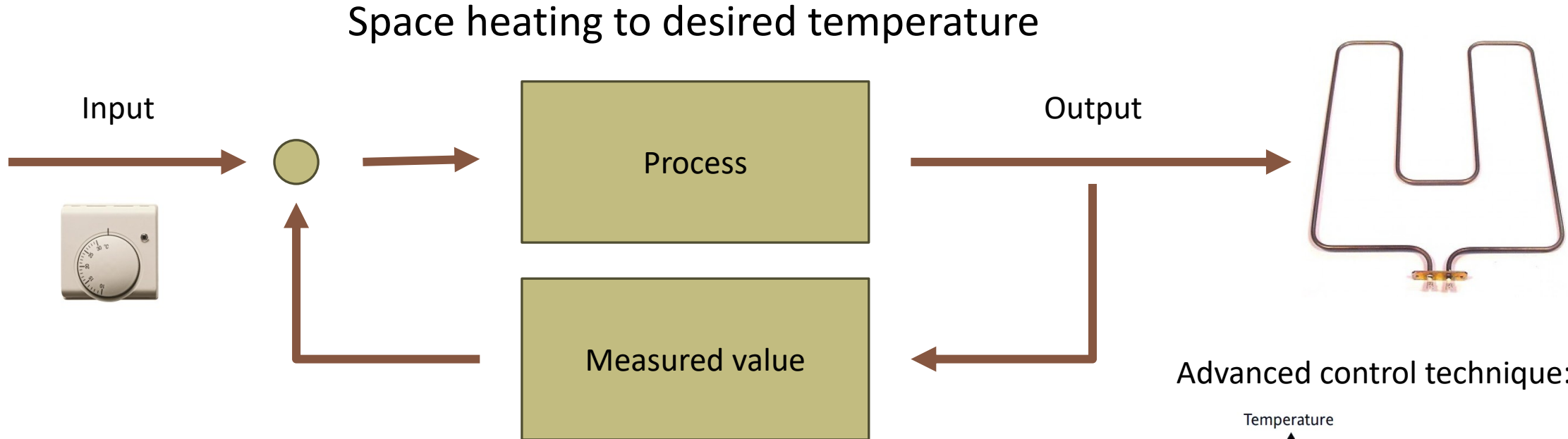
Automation system

Space heating to desired temperature



Mechatronics Automation

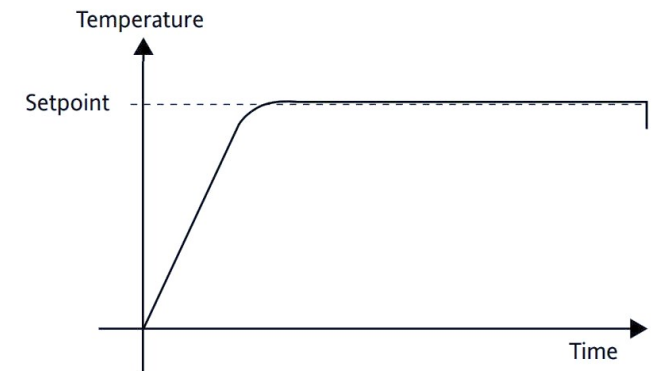
Automation system



How would we achieve more advanced control techniques?

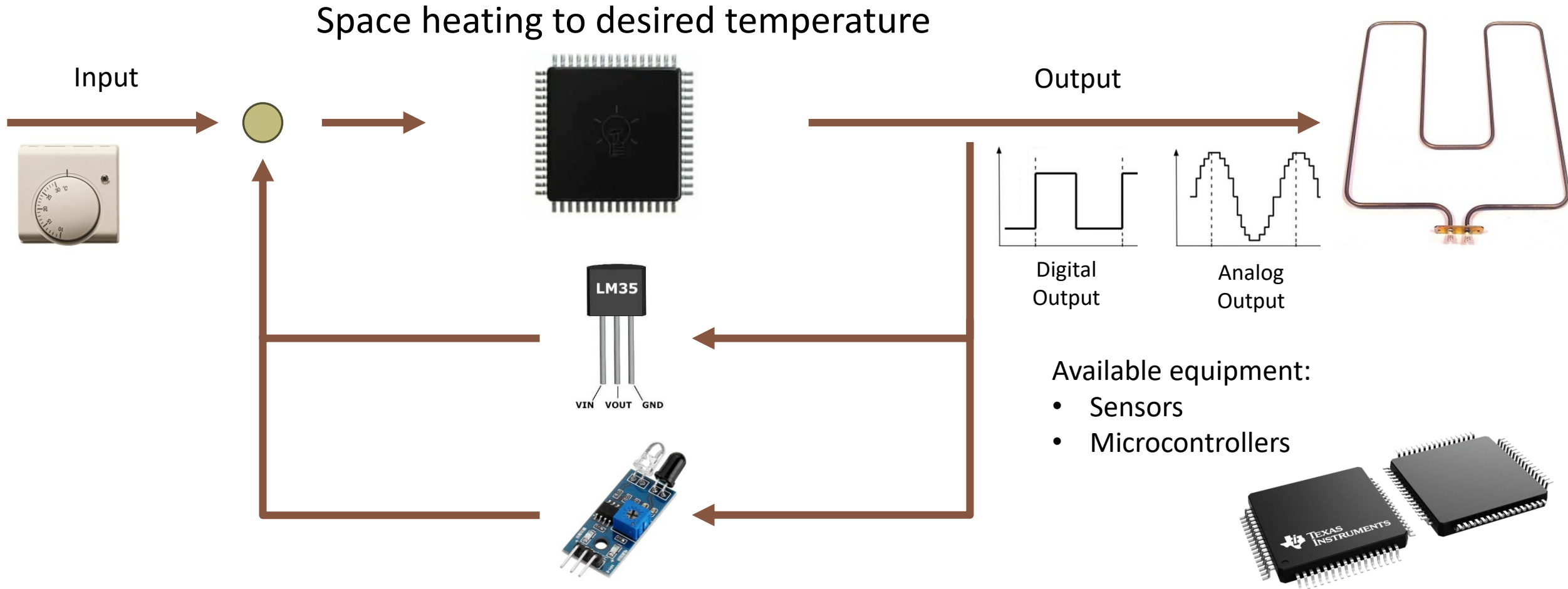
- PID Control
- Operation only when the space is not empty
- Change the desired temperature under specific cases
- Memory/history retention

Advanced control technique: PID



Mechatronics Automation

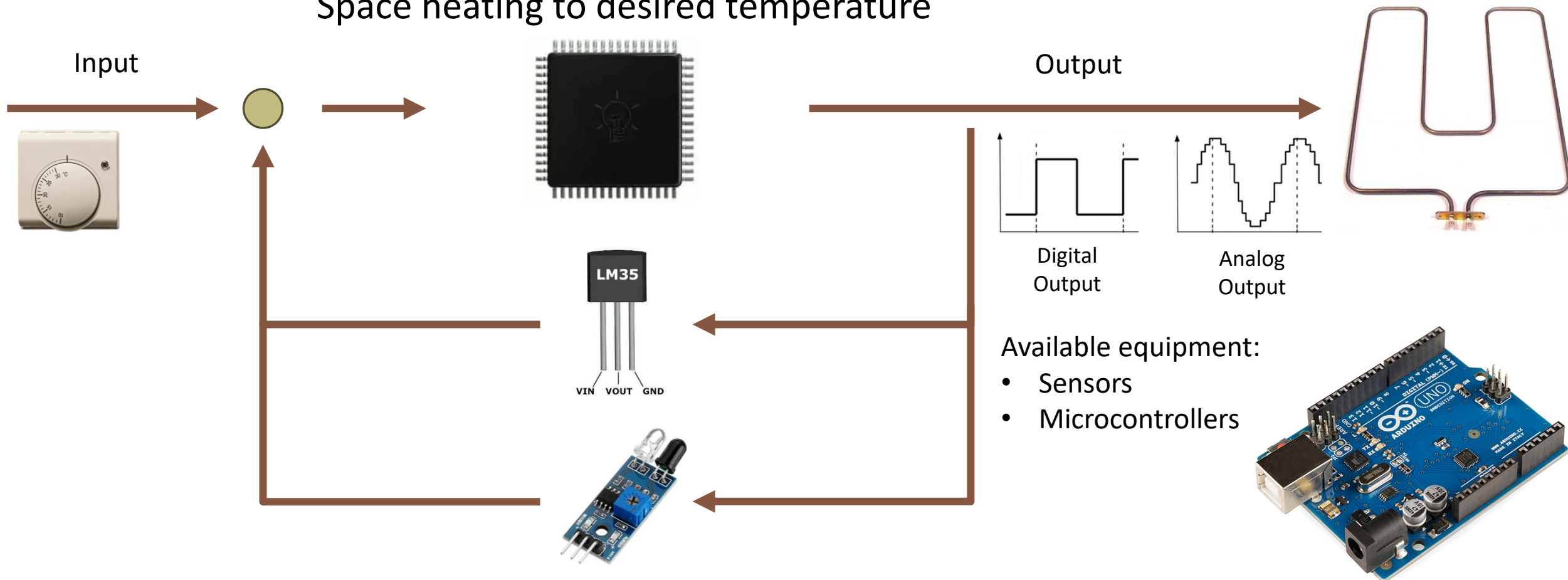
Automation system



Mechatronics Automation

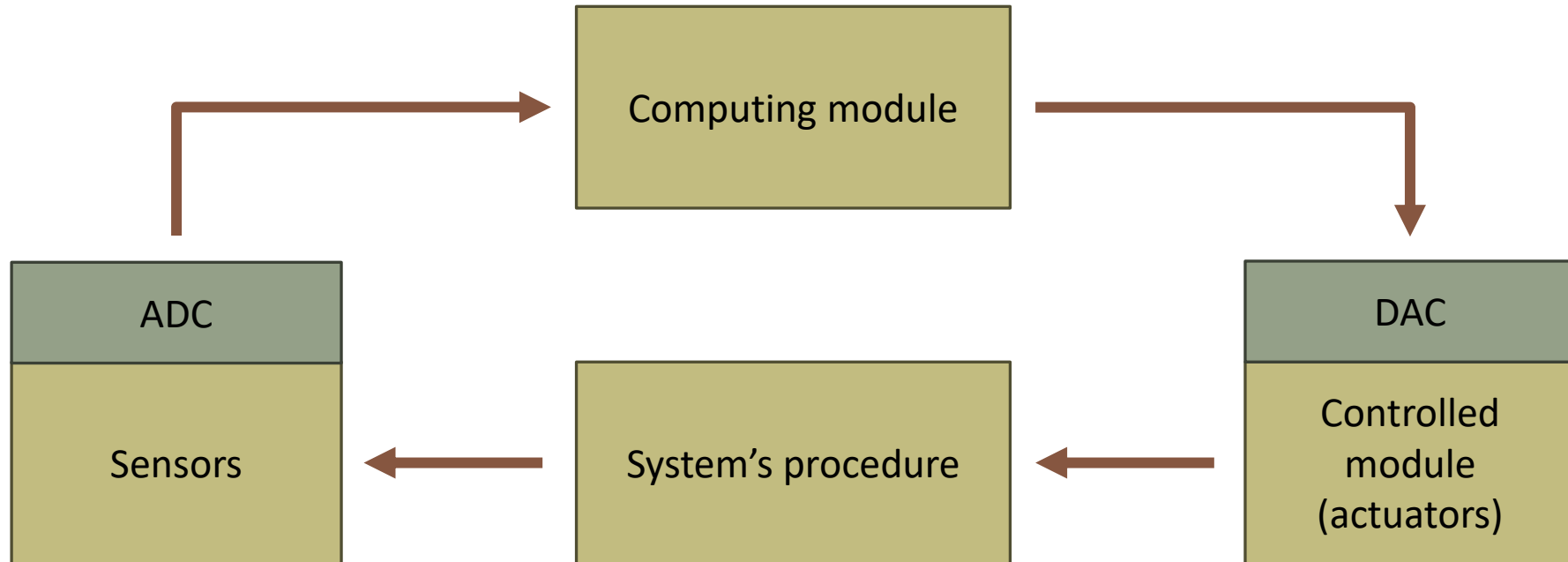
Automation system

Space heating to desired temperature



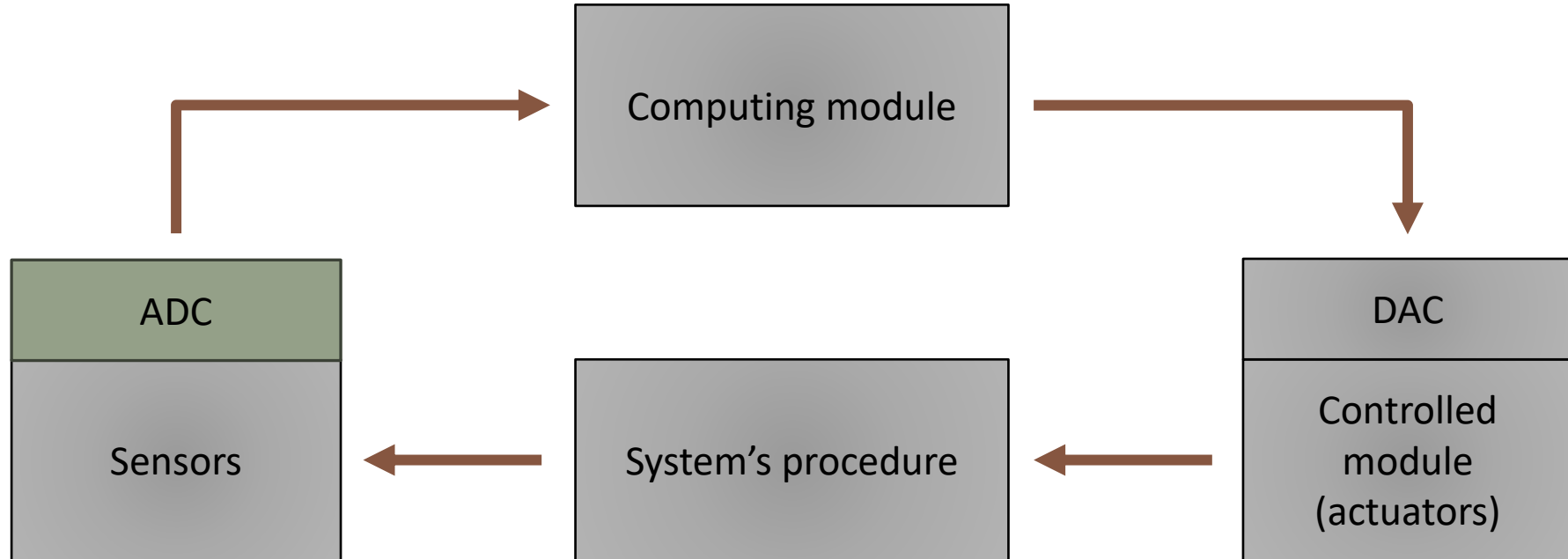
Mechatronics Automation

Control loop



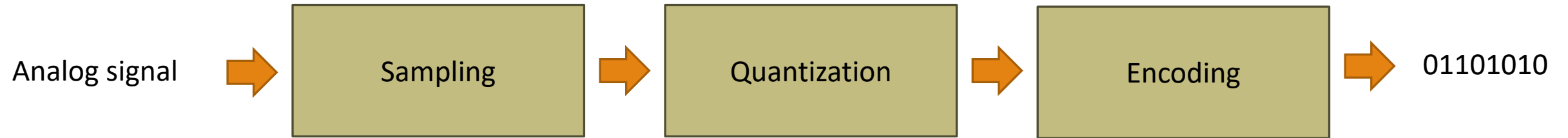
Mechatronics Automation

Control loop



Mechatronics Automation

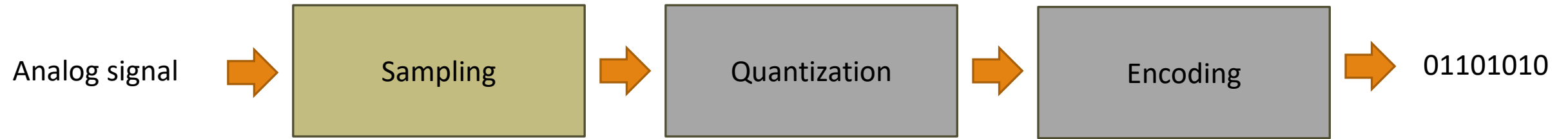
Analog to Digital Converter (ADC)



- Goal:
 - For an analog input signal
 - Produce the respective digital encoding

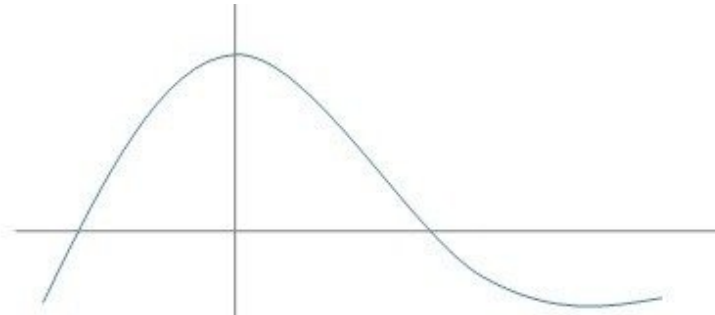
Mechatronics Automation

Analog to Digital Converter (ADC)

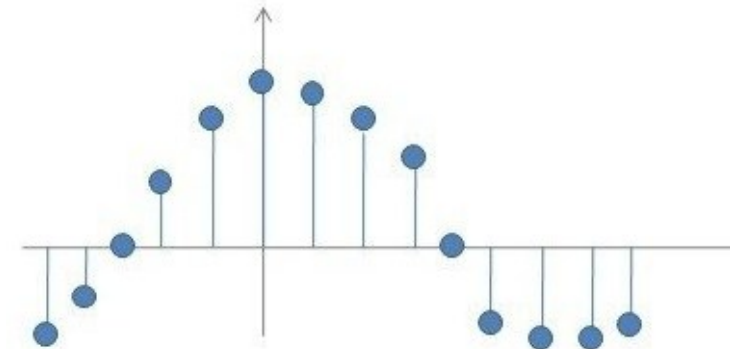


- Goal :
 - Convert a continuous input signal
 - In a discrete output signal

Continuous Signal?

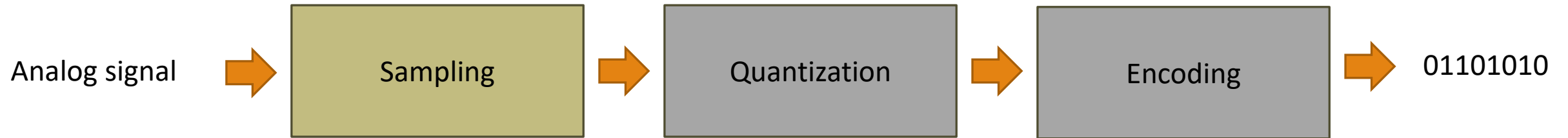


Discrete Signal?



Mechatronics Automation

Analog to Digital Converter (ADC)



- Taking samples from an analog signal at specified time intervals

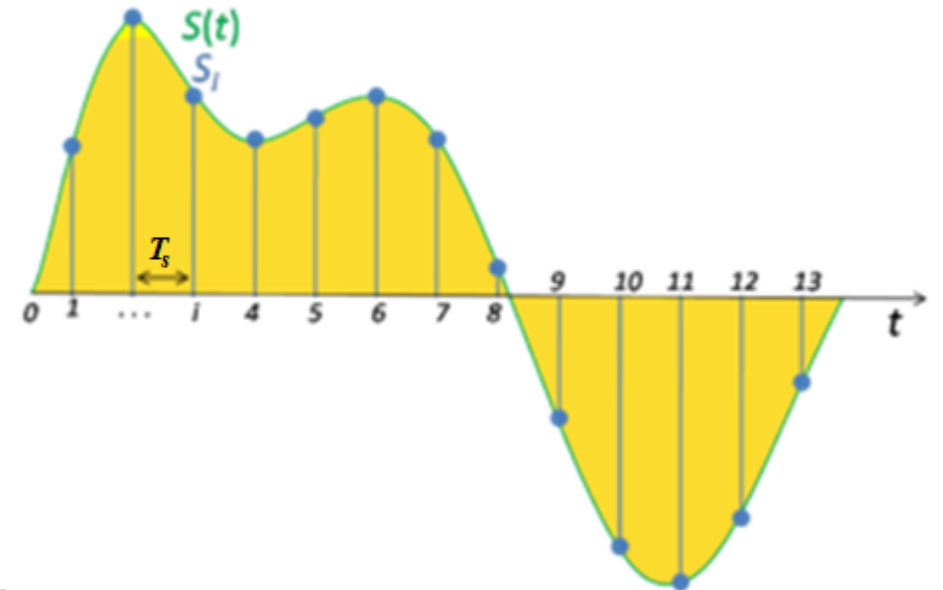
- Sampling period T_s
- Sampling frequency f_s

- Shannon's theorem: $f_s \geq 2 * f_{max}$

- Nyquist Frequency:
The highest frequency that can be sampled
 $f_n = f_s / 2$

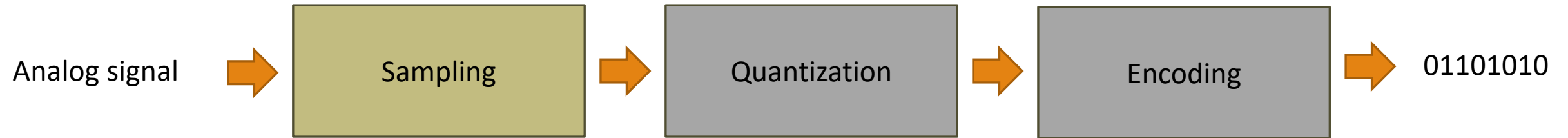
- Result

- Continuous in time analog signal $\rightarrow$
Discrete signal (discrete in time but continuous in amplitude)



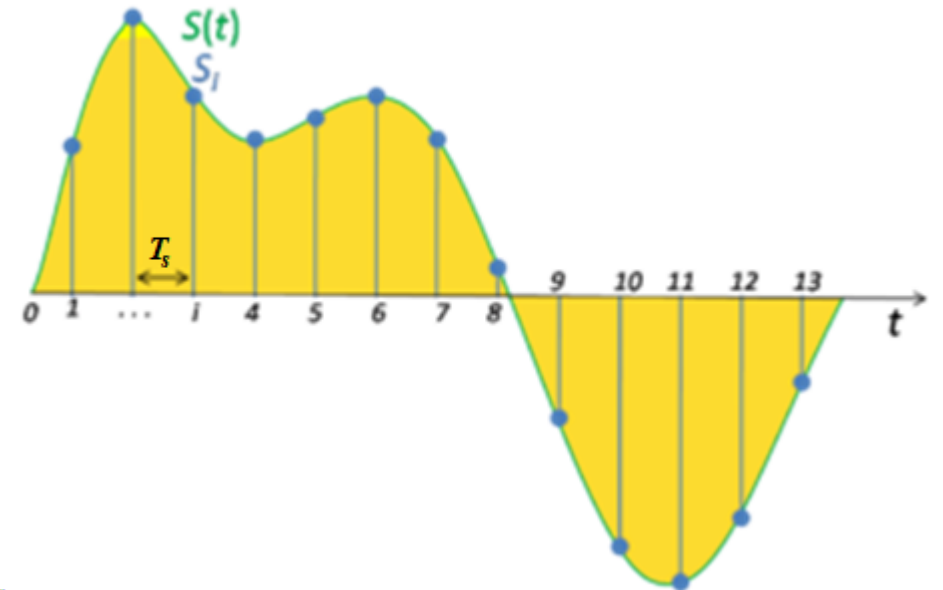
Mechatronics Automation

Analog to Digital Converter (ADC)



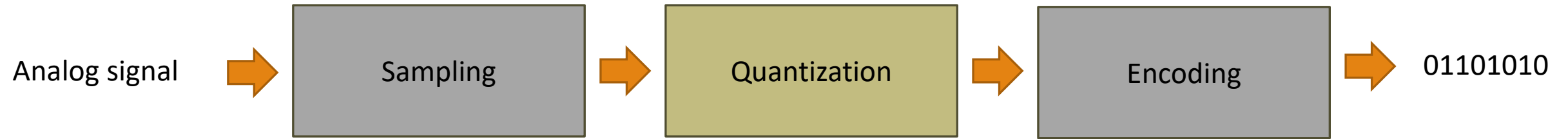
Is a discrete signal also digital?

- Discrete time signal
VS
- Discrete value signal



Mechatronics Automation

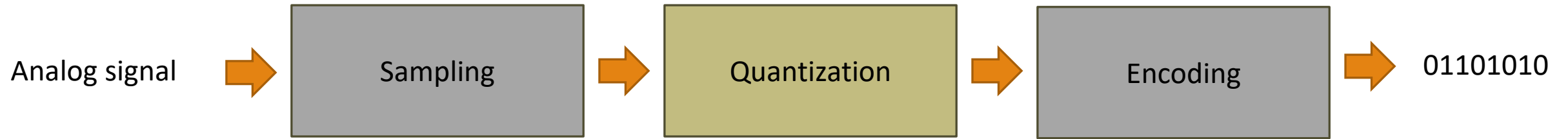
Analog to Digital Converter (ADC)



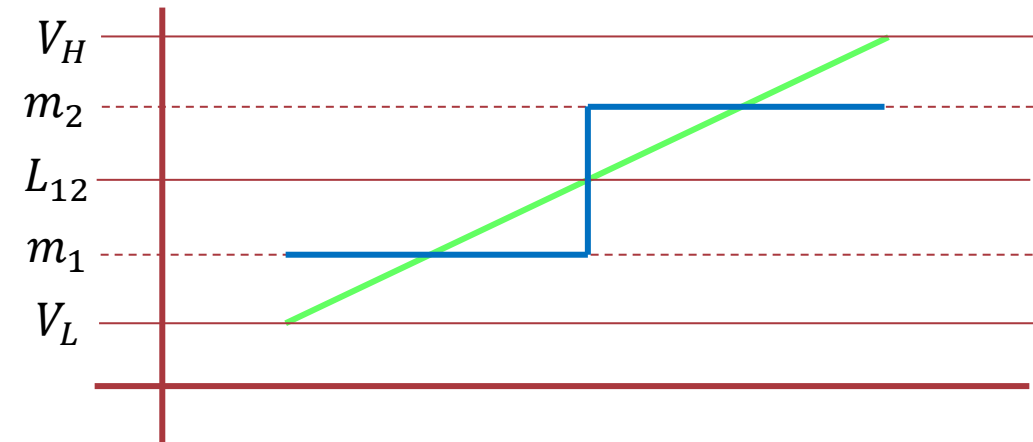
- Goal:
 - Categorization of input signal values
 - at different output levels

Mechatronics Automation

Analog to Digital Converter (ADC)

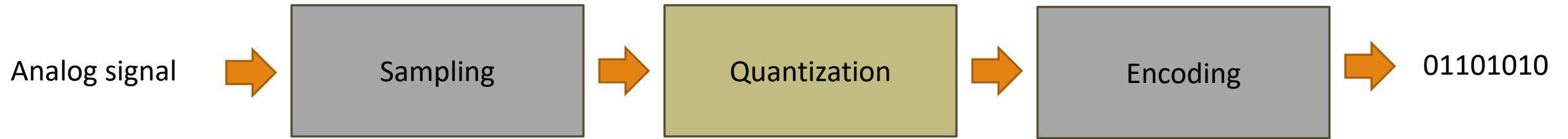


- Suppose I want to divide an input signal into two categories
 - Low Level and
 - High Level
- Steps:
 - What is the range of the signal? $\rightarrow V_L$ and V_H
 - How many are the categories (levels)? $\rightarrow$ Let 2: m_1 και m_2
 - How do I want to distribute them? $\rightarrow$ Let uniformly
 - How many threshold values should I compare with?
 $\rightarrow$ For 2 levels: 1 (L_{12})

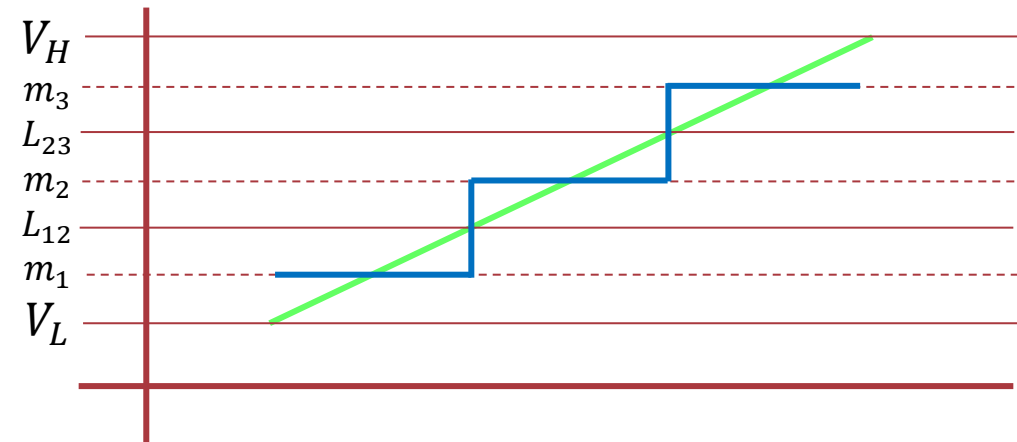


Mechatronics Automation

Analog to Digital Converter (ADC)

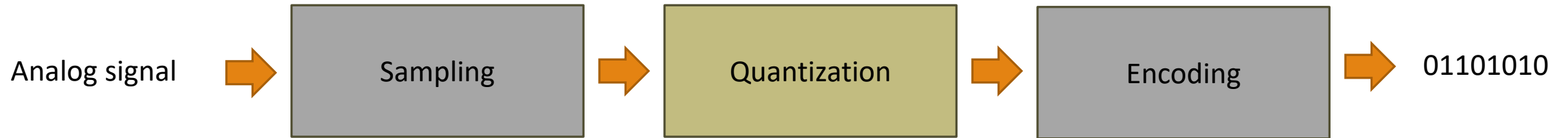


- Suppose I want to divide an input signal into three categories
- Steps:
 - What is the range of the signal?
 - How many are the categories (levels)?
 - How do I want to distribute them?
 - How many threshold values should I compare with?

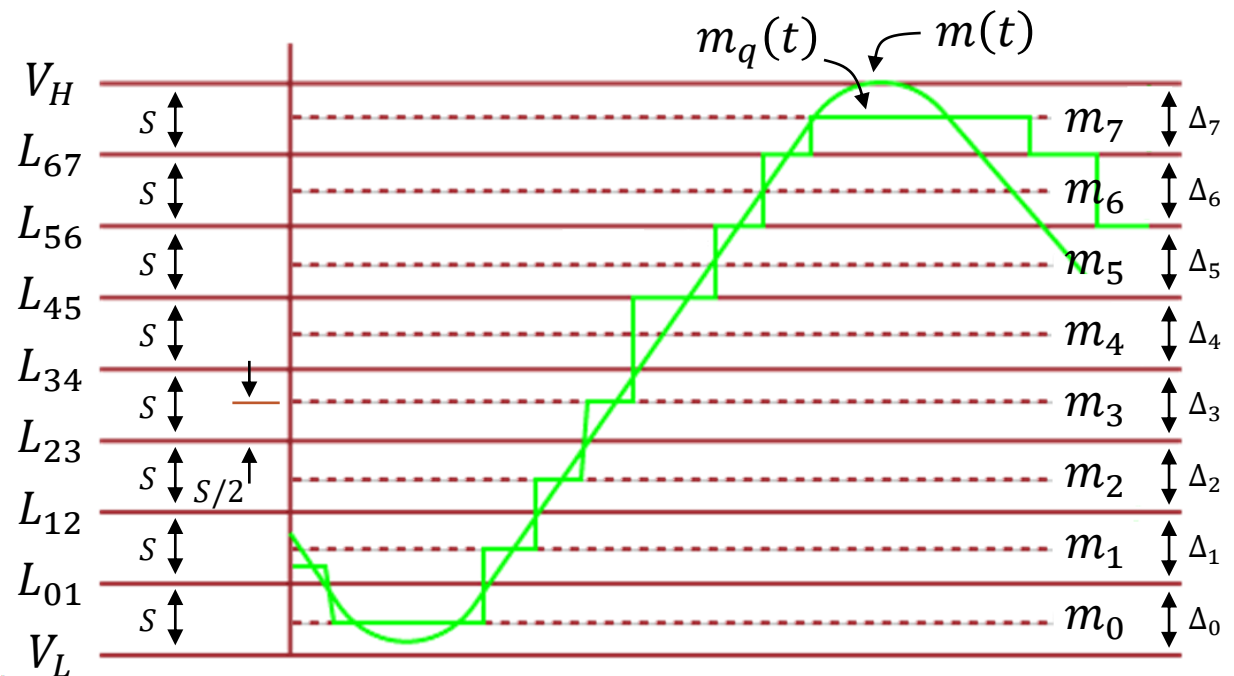


Mechatronics Automation

Analog to Digital Converter (ADC)

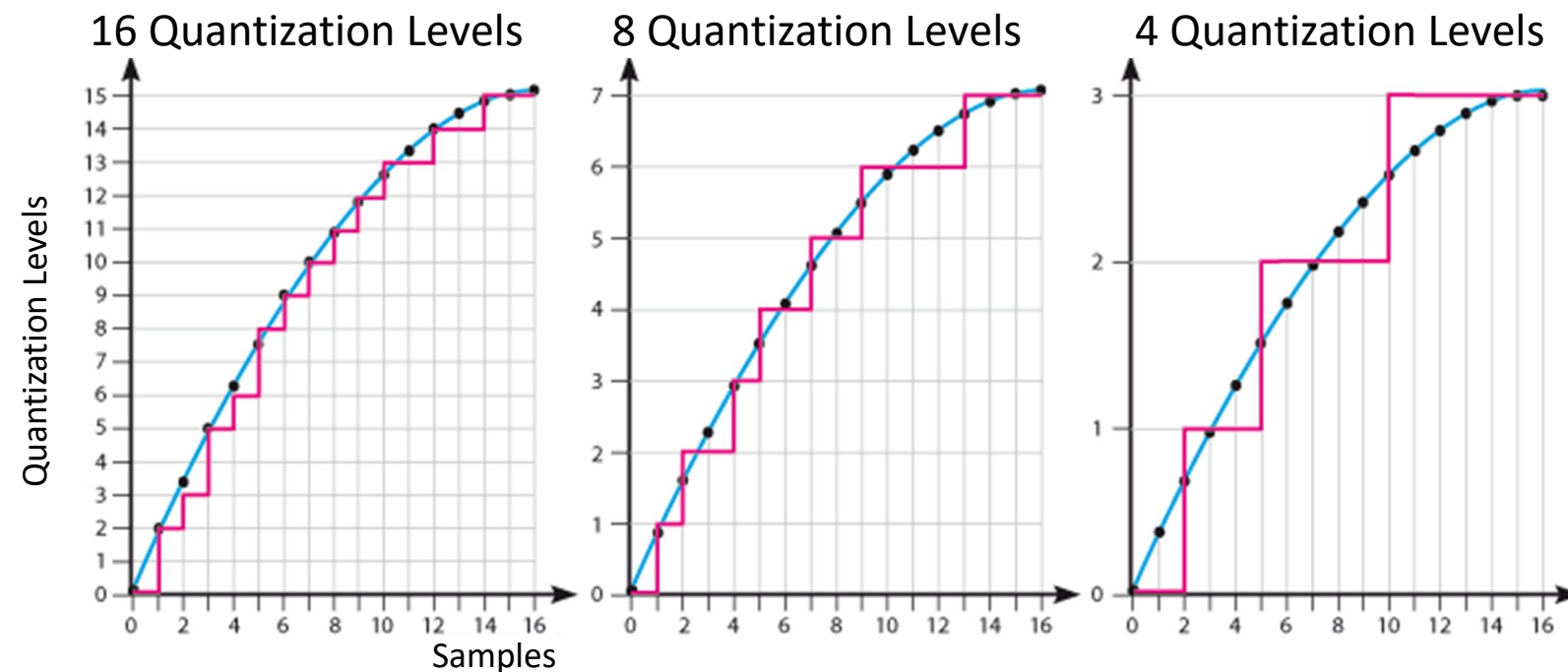
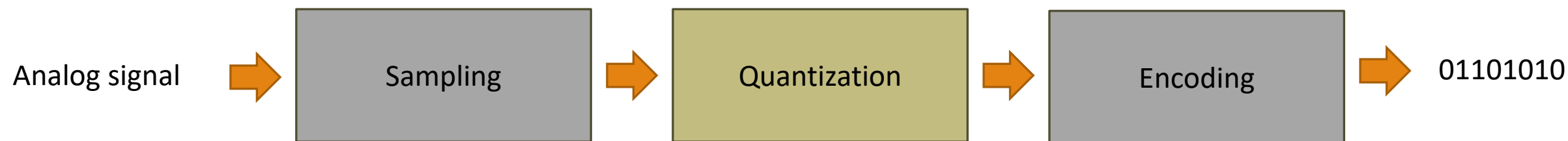


- Intervals and levels:
 - $M = \text{Intervals } (\Delta_0, \Delta_1, \dots, \Delta_{M-1})$
 - $M = \text{Quantization levels } (m_0, m_1, \dots, m_{M-1})$
in the middle of the intervals
- Quantization interval distribution:
Equal intervals $\rightarrow$ Uniformly quantized signal
 - Interval size: $S = \frac{V_H - V_L}{M}$
- $m_q(t) = \text{closest level to } m(t)$
- Quantization Error:
 - $e = m(t) - m_q(t), |e| \leq S/2$



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Analog to Digital Converter (ADC)

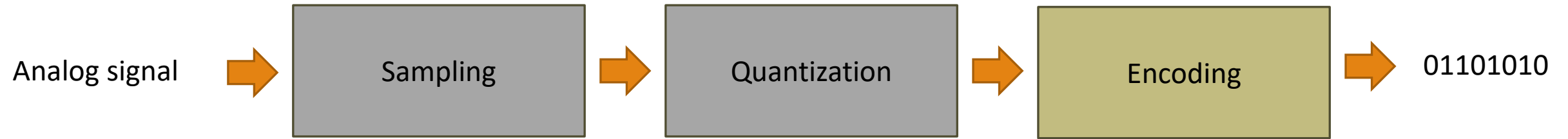


For the same signal range, the following holds:

- $S_{16} < S_8 < S_4$
- $e_{16} < e_8 < e_4$

Mechatronics Automation

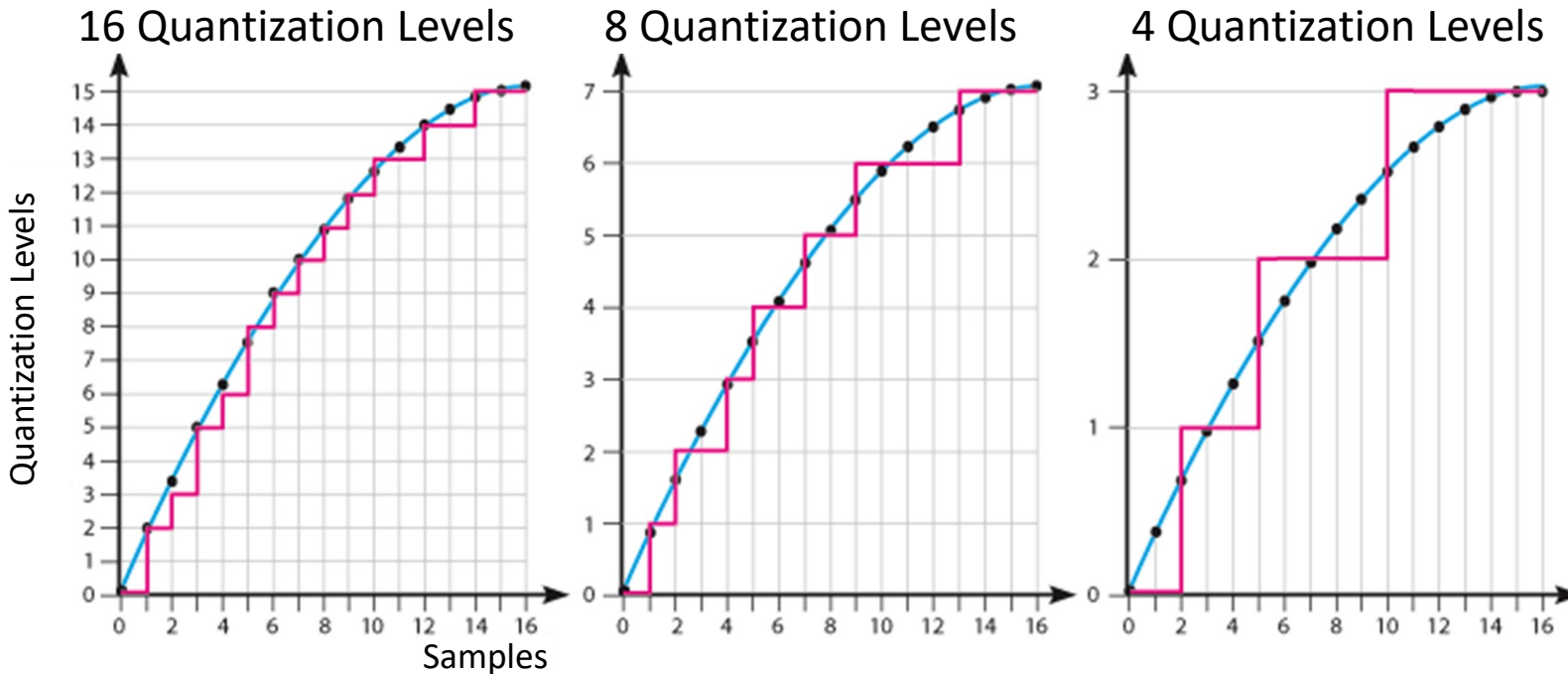
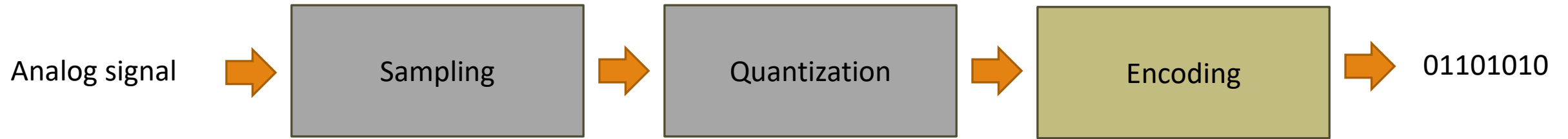
Analog to Digital Converter (ADC)



- Goal:
 - Assign each output level
 - To a unique binary code

Mechatronics Automation

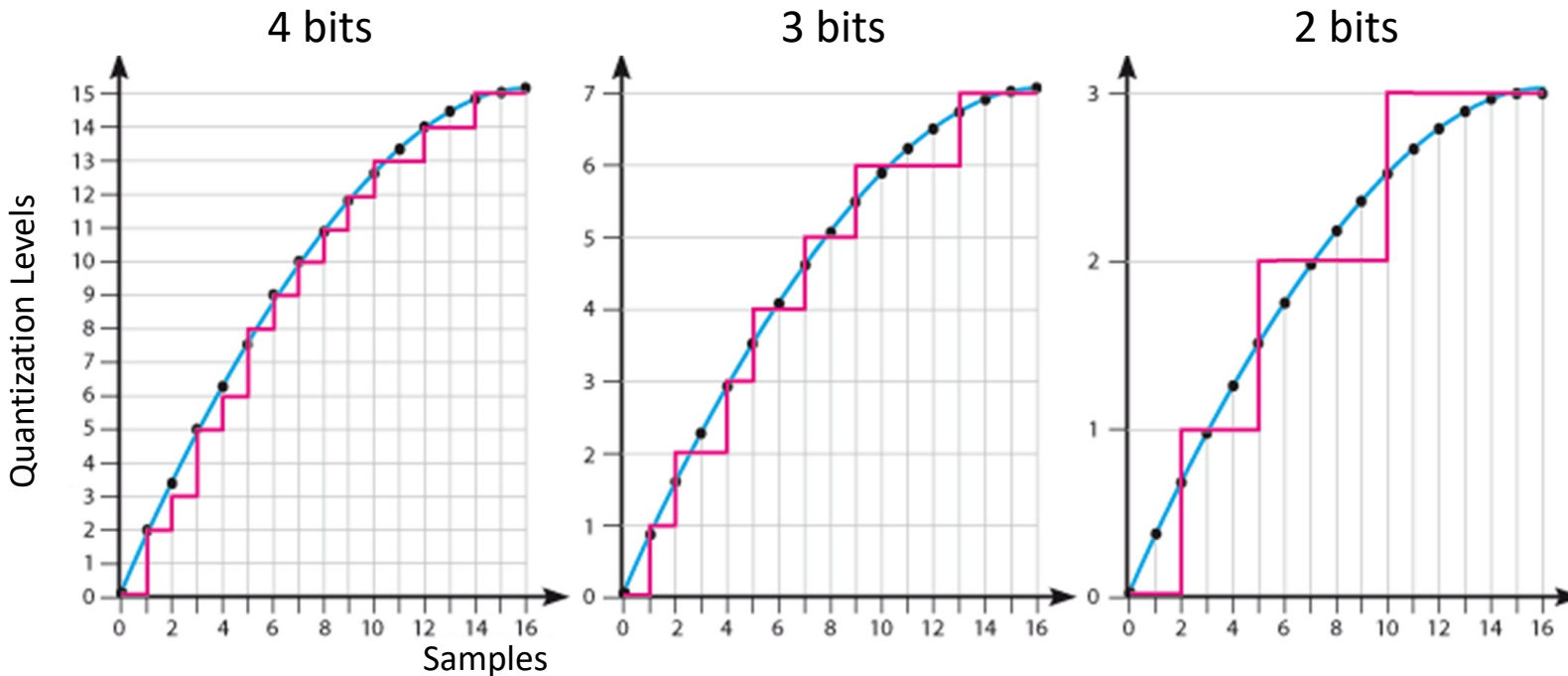
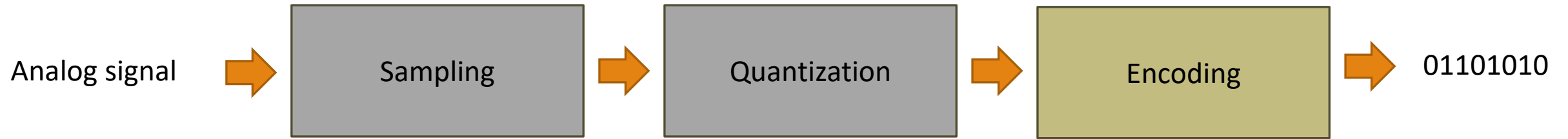
Analog to Digital Converter (ADC)



- How many bits do we need to represent 4 levels?
- How many bits do we need to represent 8 levels?
- How many bits do we need to represent 16 levels?

Mechatronics Automation

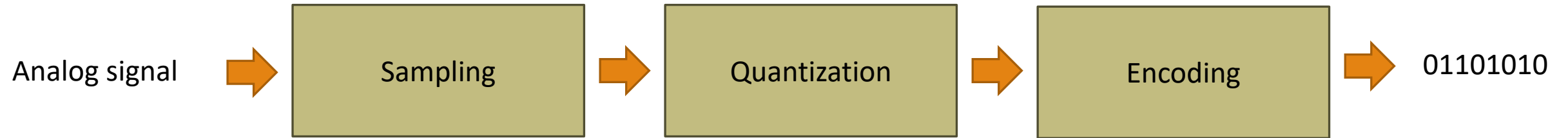
Analog to Digital Converter (ADC)



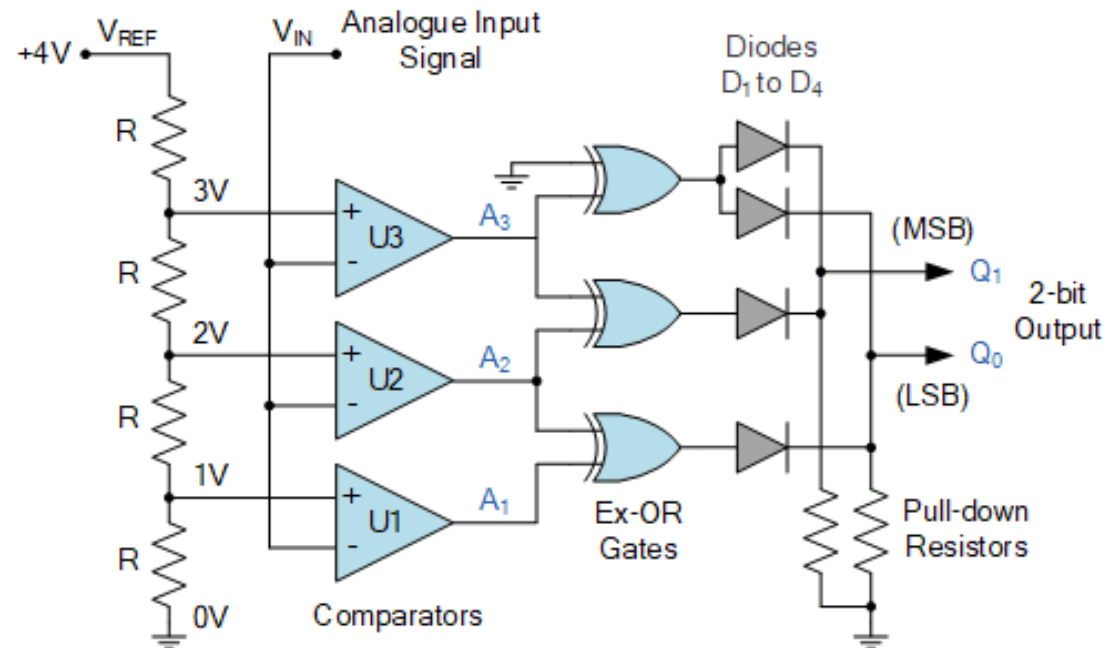
- How many bits do we need to represent 4 levels?
- How many bits do we need to represent 8 levels?
- How many bits do we need to represent 16 levels?

Mechatronics Automation

Analog to Digital Converter (ADC)

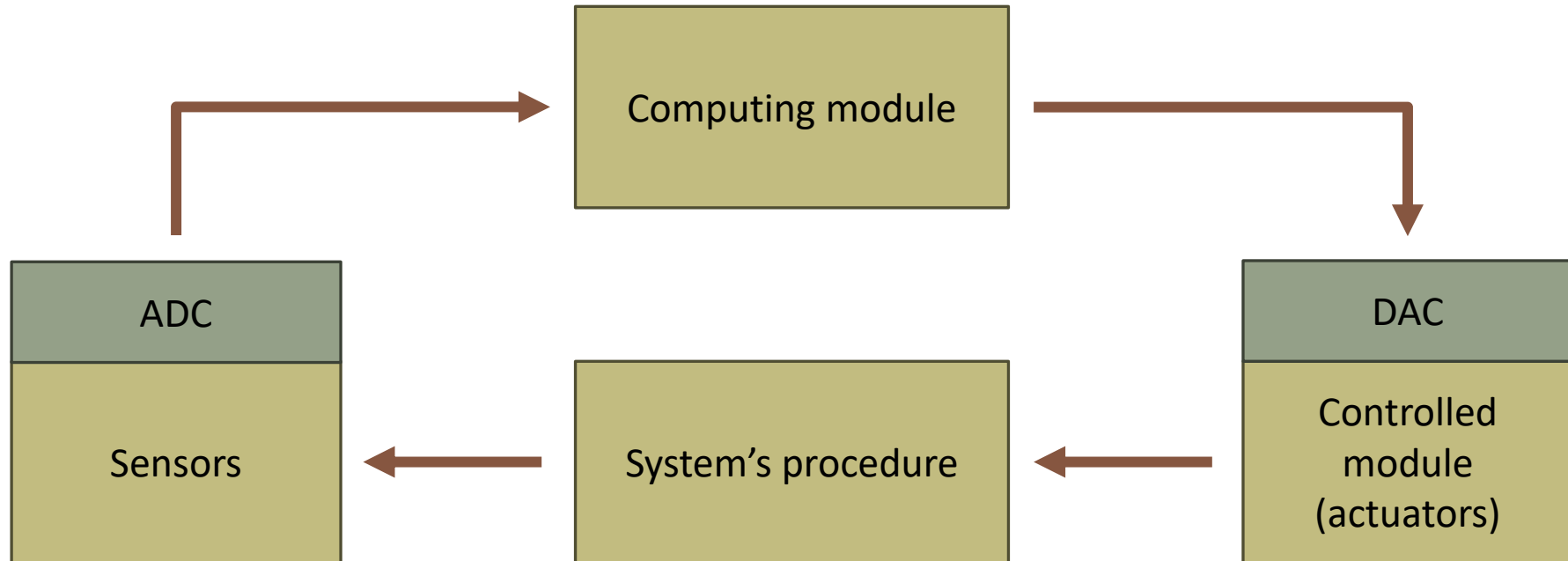


Simple ADC circuit example



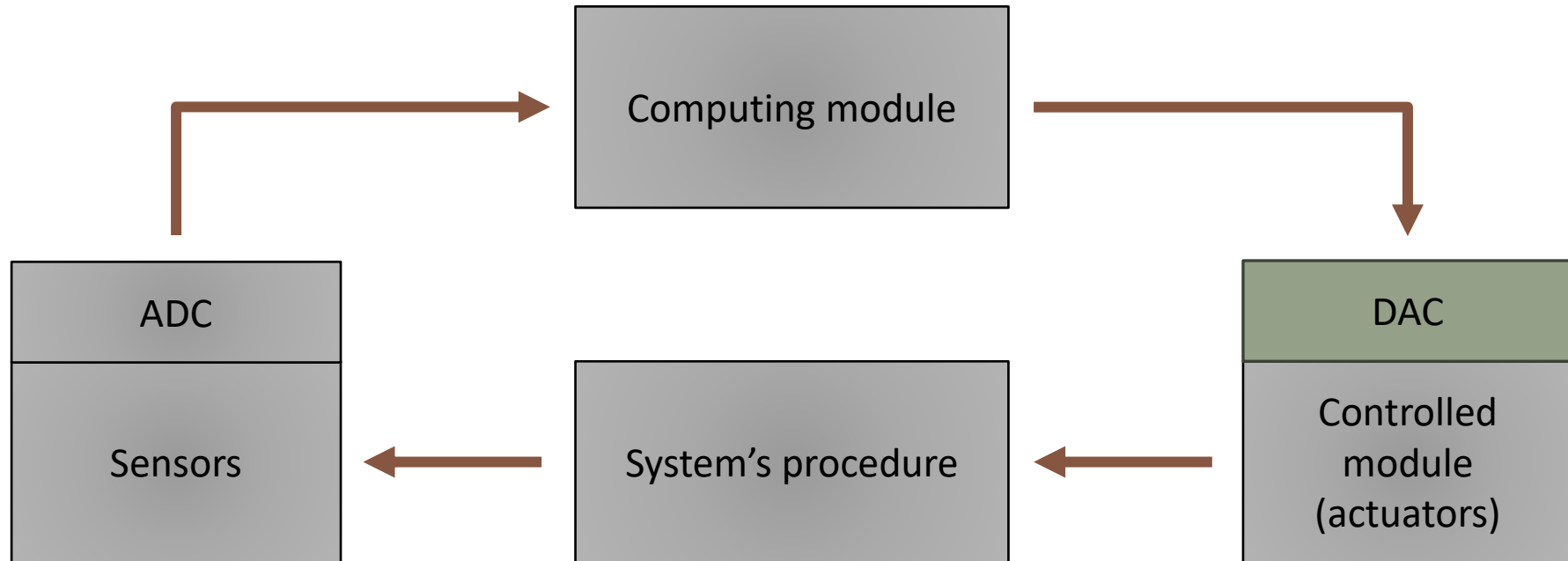
Mechatronics Automation

Control loop



Mechatronics Automation

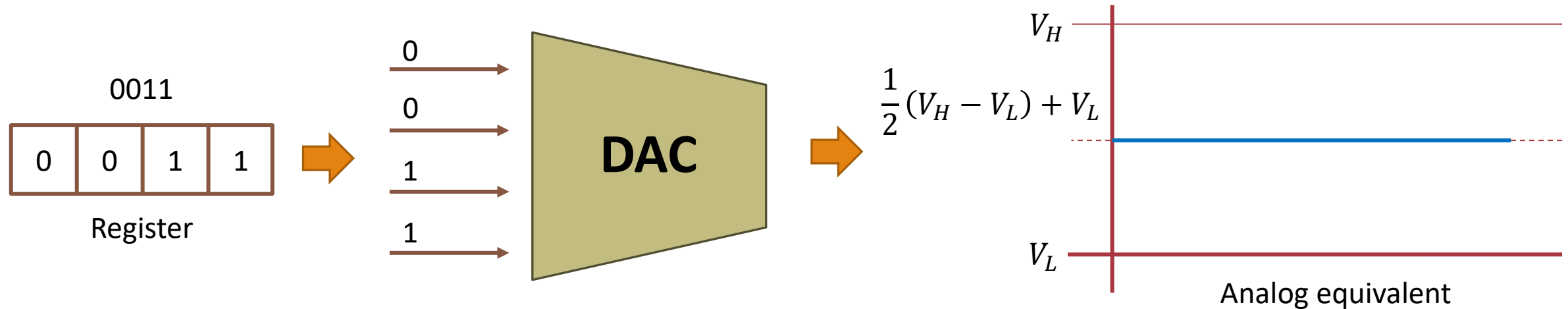
Control loop



Mechatronics Automation

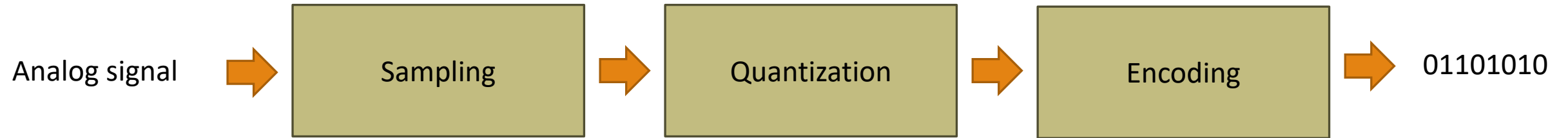
Digital to Analog Converters (DAC)::

Each digital input value is converted into a corresponding output voltage value between the V_L and V_H .



Mechatronics Automation

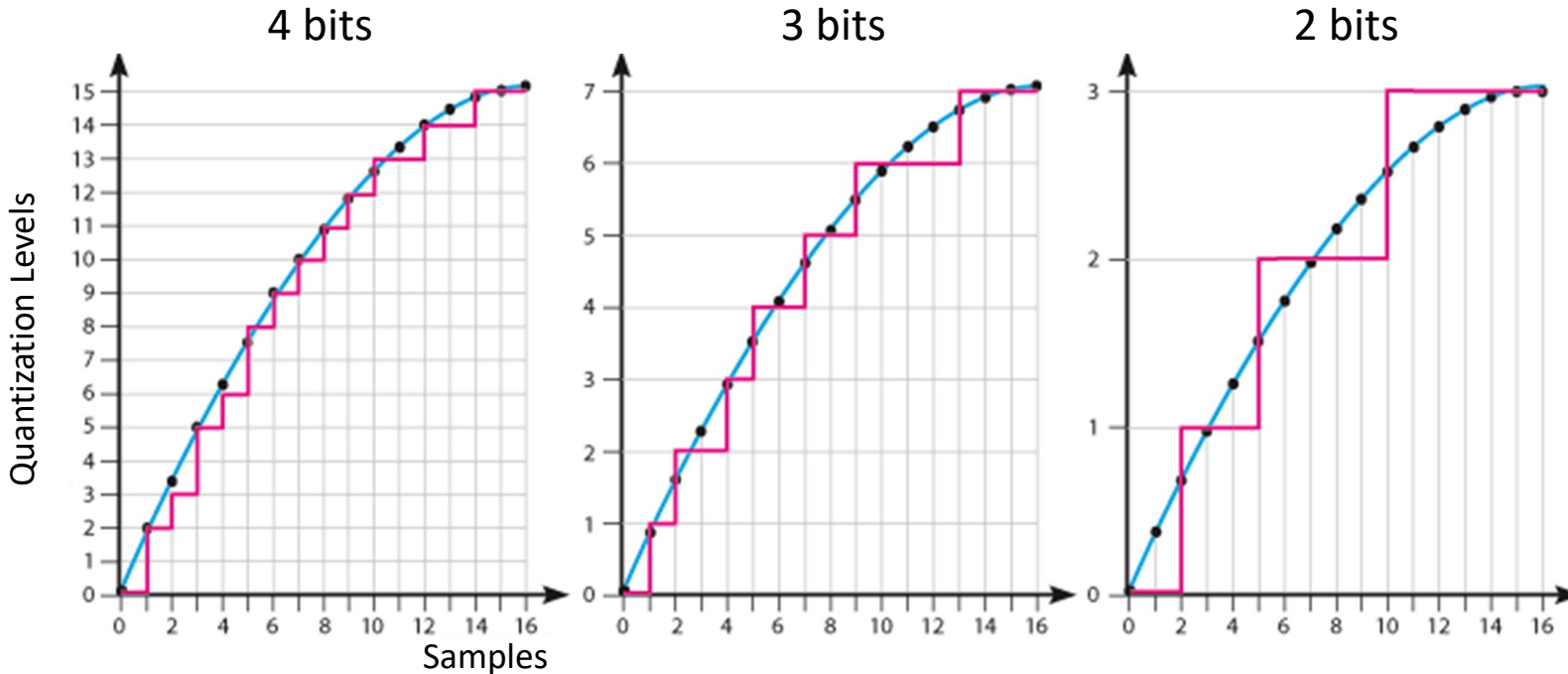
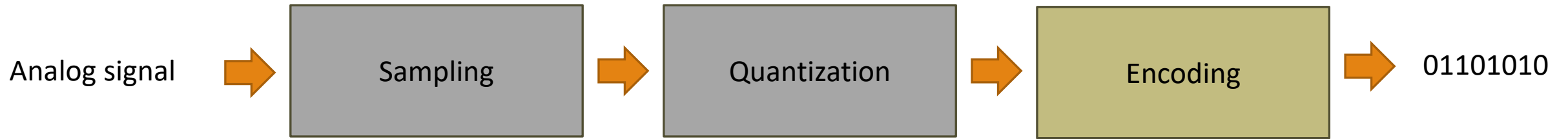
How do we achieve the reverse ADC process?



Mechatronics Automation

How do we achieve the reverse ADC process?

Digitalization:



- Number of bits: n
- Available quantization levels: 2^n
- Range of digital representation: $0, \dots, 2^n - 1$
- Digital equivalent of input signal:
$$b = ((m_q(t) - V_L) / (V_H - V_L)) * (2^n - 1)$$
- If $V_L = 0$:
$$b = (m_q(t) / V_H) * (2^n - 1)$$

$$b = (m_q(t) / V_{ref}) * (2^n - 1)$$

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How do we achieve the reverse ADC process?

Decoding: Calculation of corresponding analogue voltage

- Analogue voltage value V_{out} with respect to the digital entry value b :

$$b = \frac{V_{out} - V_L}{V_H - V_L} * (2^n - 1) \Rightarrow$$

$$b * (V_H - V_L) = (V_{out} - V_L) * (2^n - 1) \Rightarrow$$

$$b * (V_H - V_L) = V_{out} * (2^n - 1) - V_L * (2^n - 1) \Rightarrow$$

$$V_{out} * (2^n - 1) = b * (V_H - V_L) + V_L * (2^n - 1) \Rightarrow$$

$$V_{out} = \frac{b}{2^n - 1} * (V_H - V_L) + V_L$$

- Για $V_L = 0$:

$$V_{out} = \frac{b}{2^n - 1} * V_H$$

$$V_{out} = \frac{b}{2^n - 1} * V_{ref}$$

- Για μεγάλες τιμές του n :

$$V_{out} \approx \frac{b}{2^n} * V_{ref}$$

Mechatronics Automation

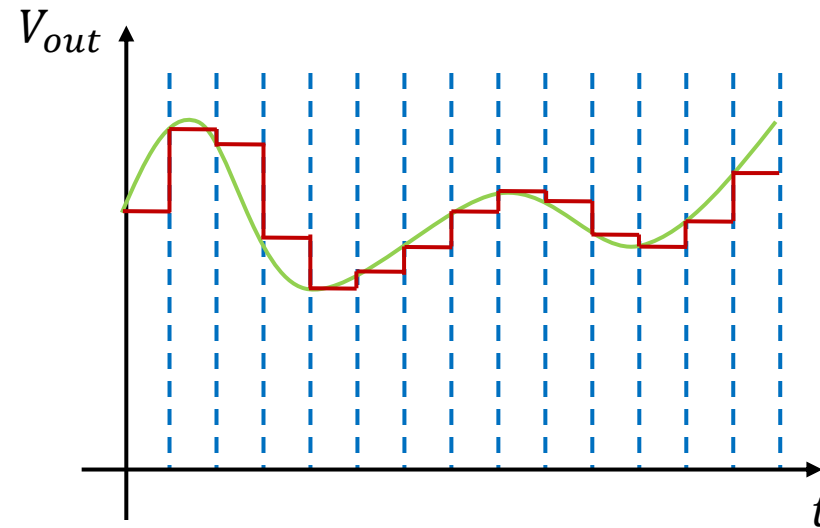
How do we achieve the reverse ADC process?

Quantization:

The output voltage (V_{out}) remains quantized at the available quantization levels depending on the number of digits

- Number of bits: n
- Available quantization levels: 2^n
- Analogue voltage range: $0, \dots, V_{ref}$
- Resolution (step): $\frac{1}{2^n} * V_{ref}$

$$V_{out} = \frac{b}{2^n} * V_{ref}$$



Mechatronics Automation

DAC:: Circuit diagram

We need a circuit that succeeds:

$$V_{out} = \frac{b}{2^n} * V_{ref}$$

Voltage Divider

However, since: $b = 2^{(n-1)}b_{n-1} + \dots + 2^3b_3 + 2^2b_2 + 2^1b_1 + 2^0b_0 \Rightarrow$

$$V_{out} = V_{ref} \left(\frac{2^{(n-1)}}{2^n} b_{n-1} + \dots + \frac{2^3}{2^n} b_3 + \frac{2^2}{2^n} b_2 + \frac{2^1}{2^n} b_1 + \frac{2^0}{2^n} b_0 \right)$$

$$V_{out} = V_{ref} \left(\frac{b_{n-1}}{2^1} + \dots + \frac{b_3}{2^{n-3}} b_3 + \frac{b_2}{2^{n-2}} + \frac{b_1}{2^{n-1}} + \frac{b_0}{2^n} \right)$$

Operational Amplifier:
Summing Amplifier

Two basic circuits:

- Binary weighted resistor DAC
- R-2R ladder DAC

Mechatronics Automation

Binary weighted resistor DAC

Operational Amplifier:

$$\frac{V_{out}}{R_f} + \frac{-V_{ref}b_0}{2^3R} + \frac{-V_{ref}b_1}{2^2R} + \frac{-V_{ref}b_2}{2^1R} + \frac{-V_{ref}b_3}{2^0R} = 0 \Rightarrow$$

$$\frac{V_{out}}{R_f} = \frac{V_{ref}b_0}{2^3R} + \frac{V_{ref}b_1}{2^2R} + \frac{V_{ref}b_2}{2^1R} + \frac{V_{ref}b_3}{2^0R} \Rightarrow$$

$$V_{out} = V_{ref} \frac{R_f}{2^3R} b_0 + V_{ref} \frac{R_f}{2^2R} b_1 + V_{ref} \frac{R_f}{2^1R} b_2 + V_{ref} \frac{R_f}{2^0R} b_3 \Rightarrow$$

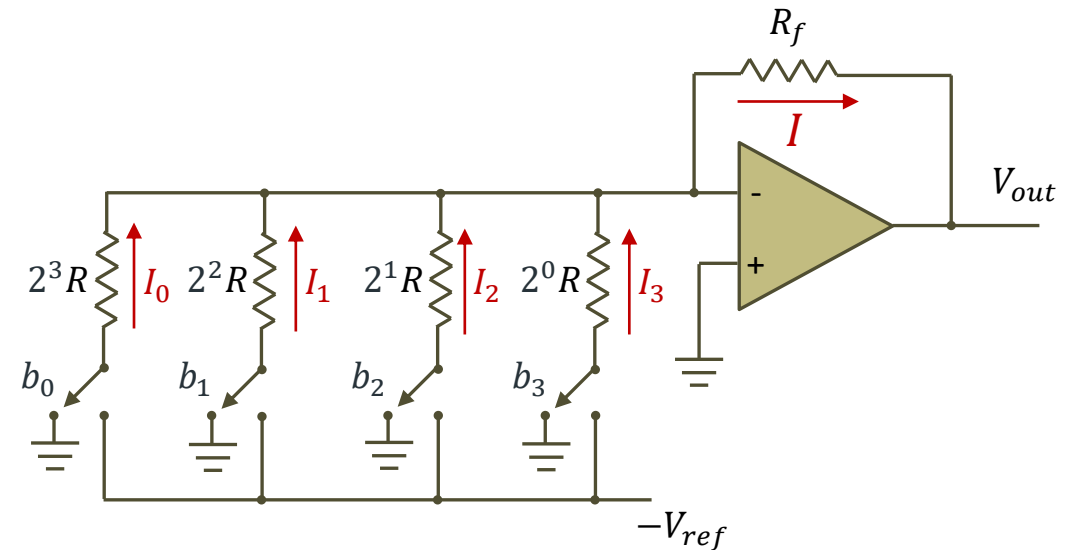
$$V_{out} = \frac{V_{ref}R_f}{R} \left(\frac{b_3}{2^0} + \frac{b_2}{2^1} + \frac{b_1}{2^2} + \frac{b_0}{2^3} \right) \xRightarrow{R=2R_f}$$

$$V_{out} = \frac{V_{ref}R_f}{2R_f} \left(\frac{b_3}{2^0} + \frac{b_2}{2^1} + \frac{b_1}{2^2} + \frac{b_0}{2^3} \right) \Rightarrow$$

$$V_{out} = \frac{V_{ref}}{2} \left(\frac{b_3}{2^0} + \frac{b_2}{2^1} + \frac{b_1}{2^2} + \frac{b_0}{2^3} \right) = V_{ref} \left(\frac{b_3}{2^1} + \frac{b_2}{2^2} + \frac{b_1}{2^3} + \frac{b_0}{2^4} \right)$$

$$V_{out} = V_{ref} \left(\frac{b_{n-1}}{2^1} + \dots + \frac{b_3}{2^{n-3}} + \frac{b_2}{2^{n-2}} + \frac{b_1}{2^{n-1}} + \frac{b_0}{2^n} \right)$$

$$n = 4: V_{out} = V_{ref} \left(\frac{b_3}{2^1} + \frac{b_2}{2^2} + \frac{b_1}{2^3} + \frac{b_0}{2^4} \right)$$



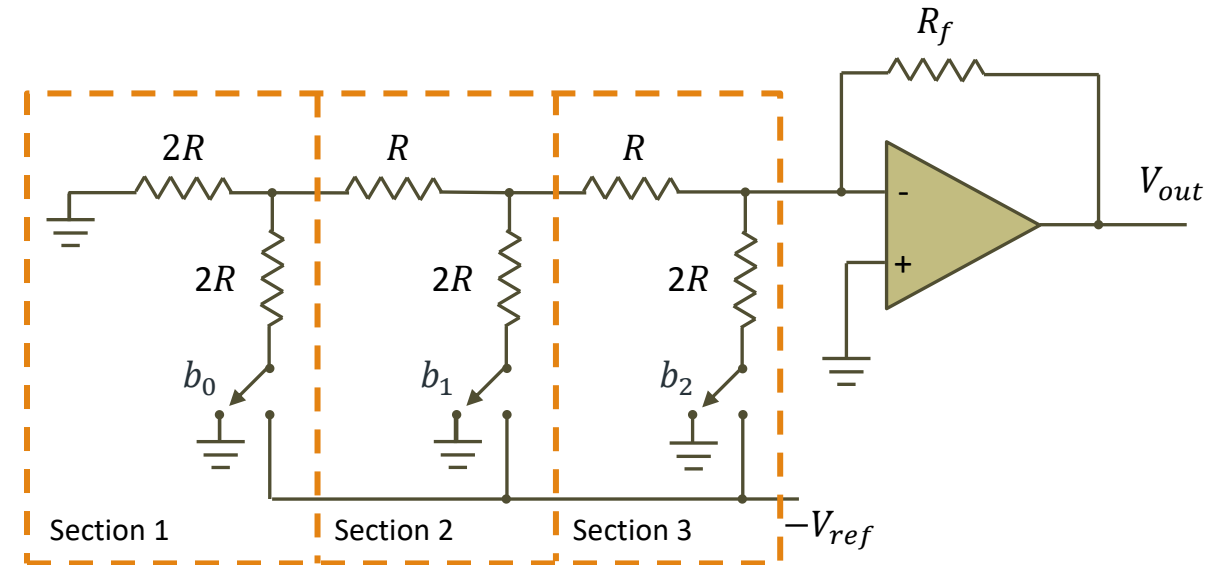
Recall that for an Operational Amplifier:

- The inverting input is virtually short-circuited to the ground without allowing the current to pass through

Mechatronics Automation

R-2R ladder DAC:: Circuit analysis for 3 bits

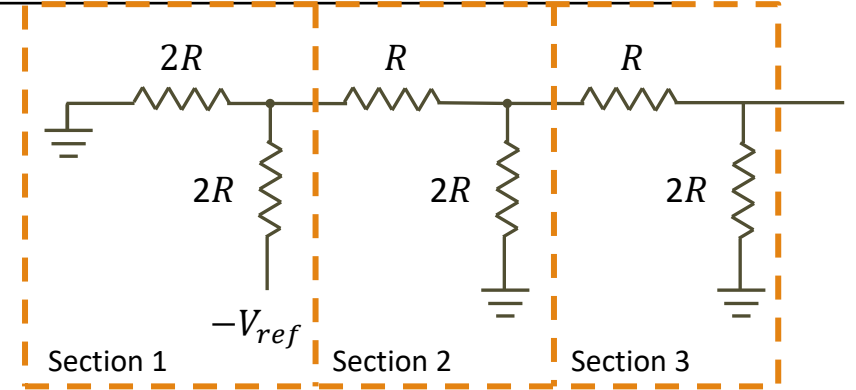
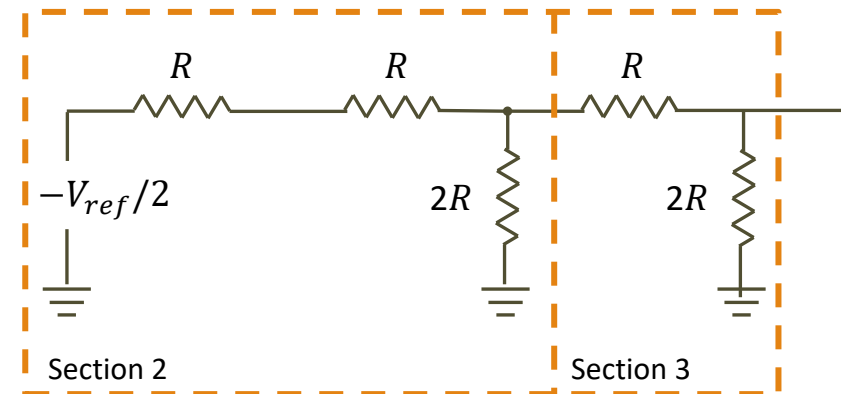
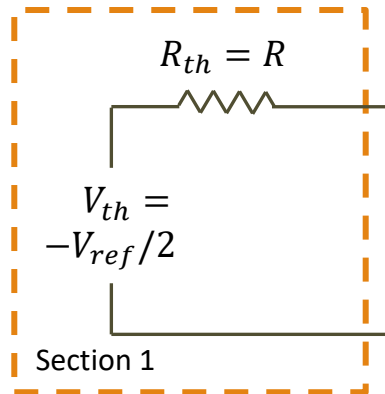
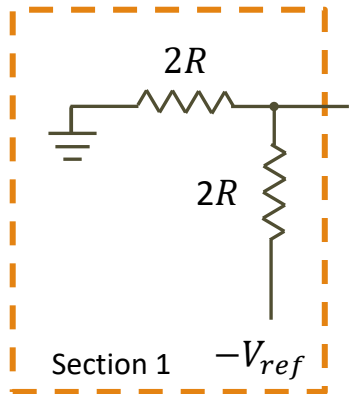
- Analysis by superposition principle and Thevenin's theorem:
 - Έστω:
 - $b_0 = 1, b_1 = 0, b_2 = 0$
 - $b_0 = 0, b_1 = 1, b_2 = 0$
 - $b_0 = 0, b_1 = 0, b_2 = 1$
 - Separate analysis for the 3 sections



Mechatronics Automation

R-2R ladder DAC:: Circuit analysis for 3 bits

- Let: $b_0 = 1, b_1 = 0, b_2 = 0$
- Section 1:

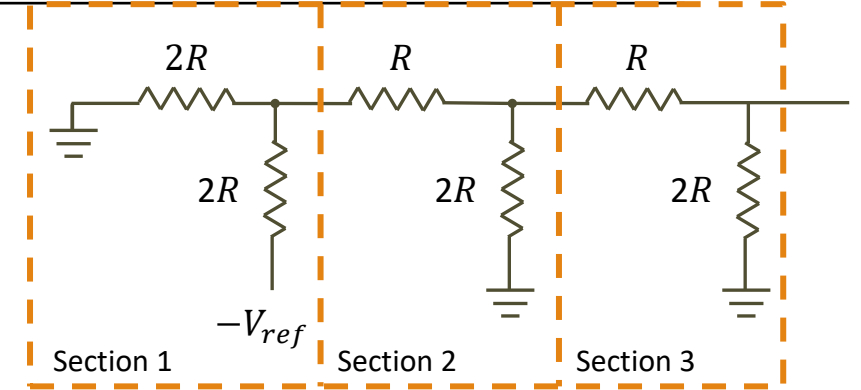
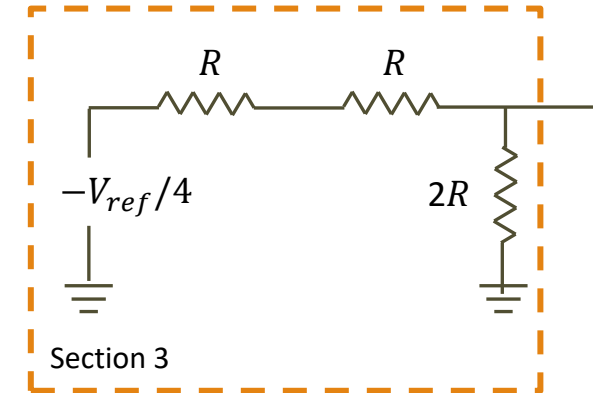
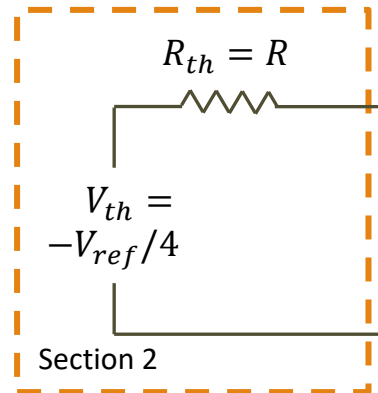
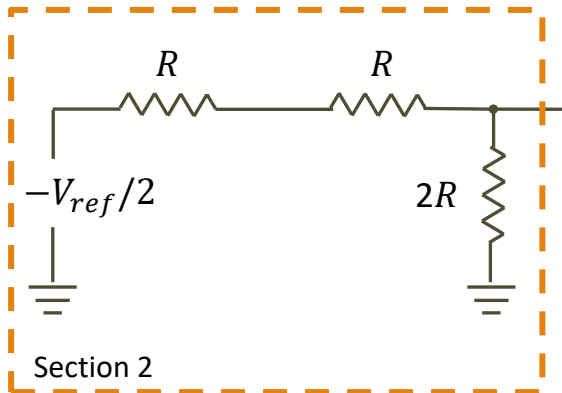


$$V_{th} = -V_{ref}/2$$
$$R_{th} = R$$

Mechatronics Automation

R-2R ladder DAC:: Circuit analysis for 3 bits

- Let: $b_0 = 1, b_1 = 0, b_2 = 0$
- Section 2:

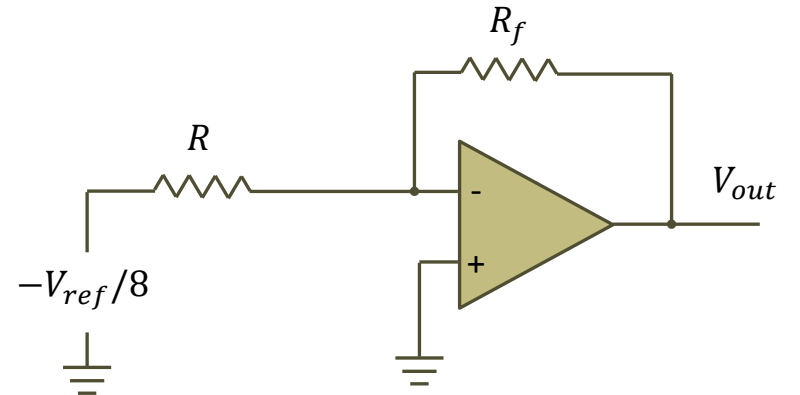
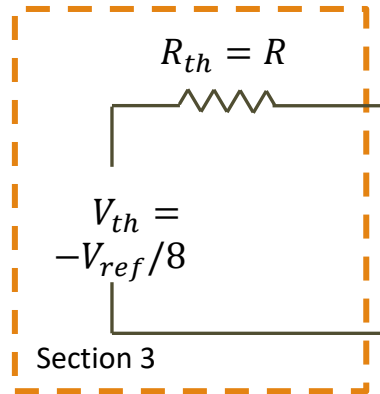
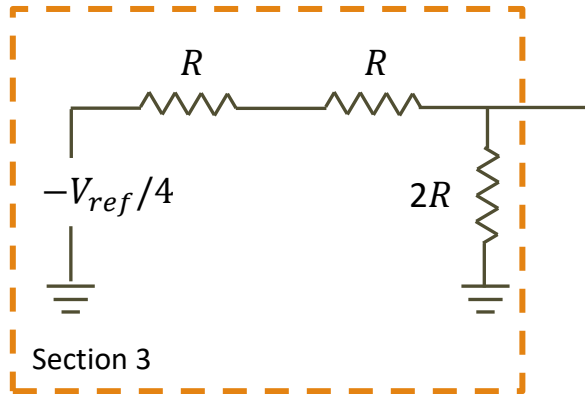


$$V_{th} = -V_{ref}/4$$
$$R_{th} = R$$

Mechatronics Automation

R-2R ladder DAC:: Circuit analysis for 3 bits

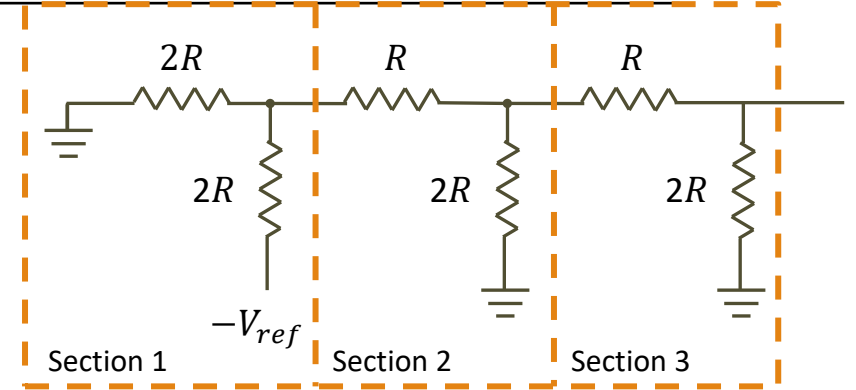
- Let: $b_0 = 1, b_1 = 0, b_2 = 0$
- Section 3:



$$V_{th} = -V_{ref}/8$$

$$R_{th} = R$$

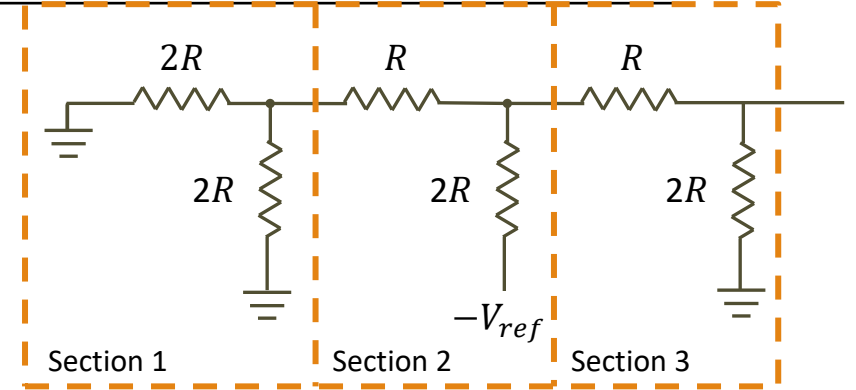
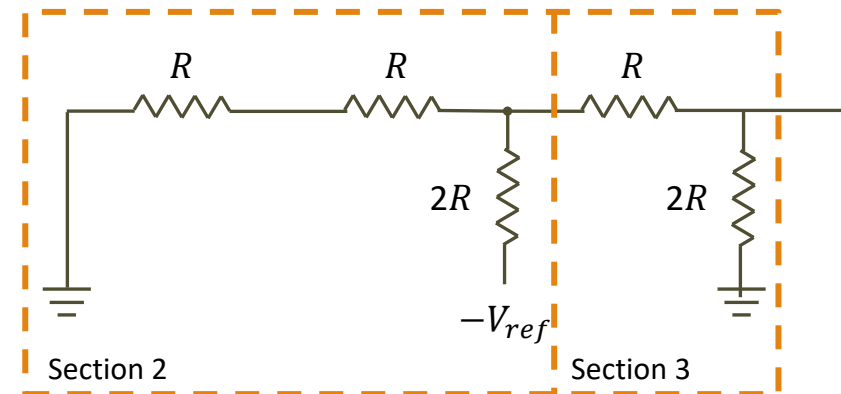
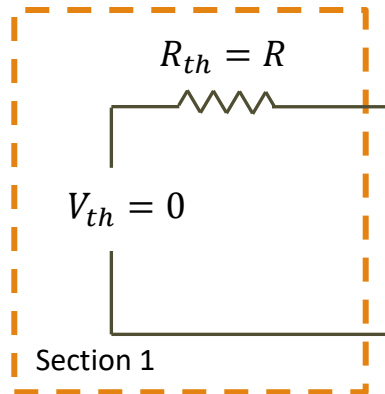
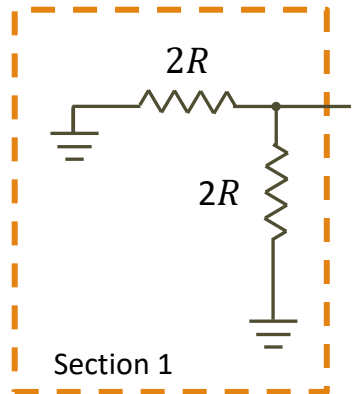
$$V_{out} = -\left(\frac{-V_{ref}}{8}\right) \frac{R_f}{R} \xrightarrow{R_f=R} V_{out} = \frac{V_{ref}}{8}$$



Mechatronics Automation

R-2R ladder DAC:: Circuit analysis for 3 bits

- Let: $b_0 = 0, b_1 = 1, b_2 = 0$
- Section 1:

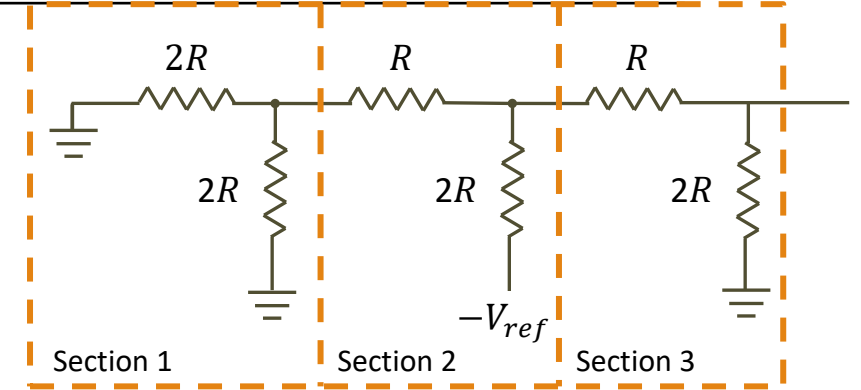
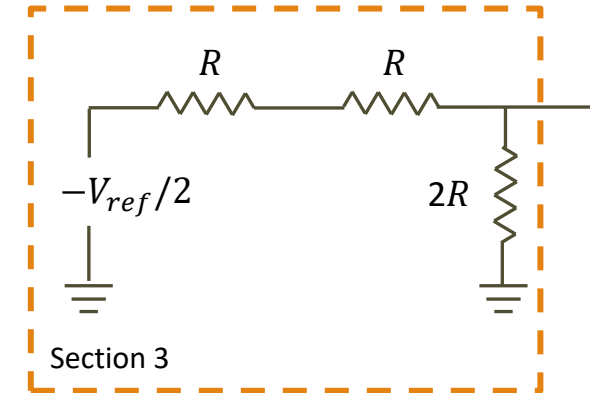
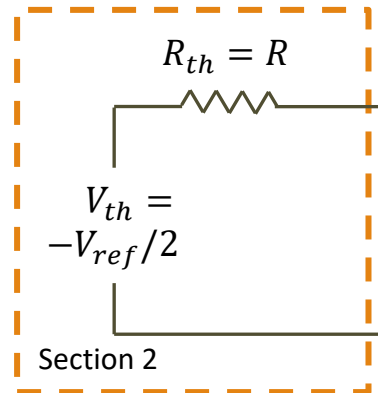
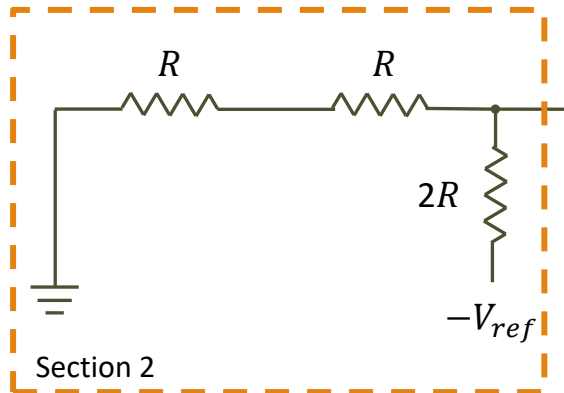


$$V_{th} = 0$$
$$R_{th} = R$$

Mechatronics Automation

R-2R ladder DAC:: Circuit analysis for 3 bits

- Let: $b_0 = 0, b_1 = 1, b_2 = 0$
- Section 2:

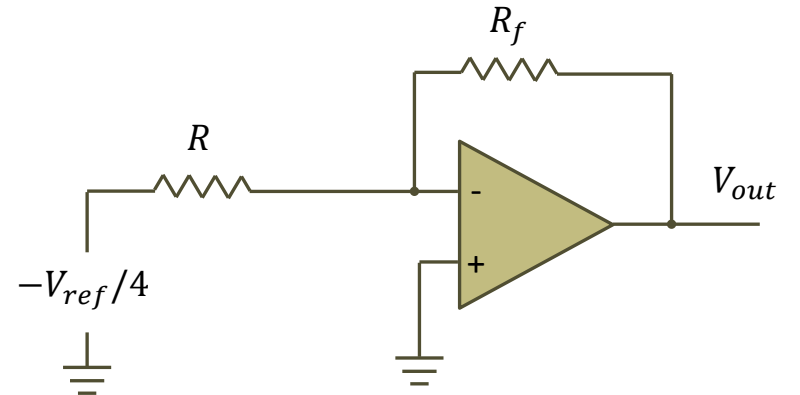
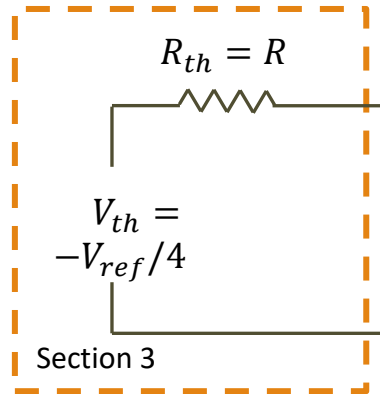
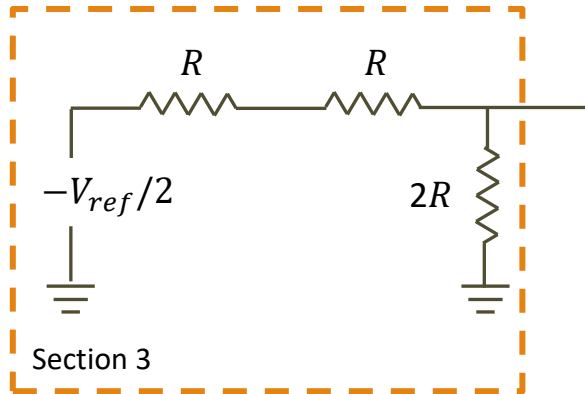


$$V_{th} = -V_{ref}/2$$
$$R_{th} = R$$

Mechatronics Automation

R-2R ladder DAC:: Circuit analysis for 3 bits

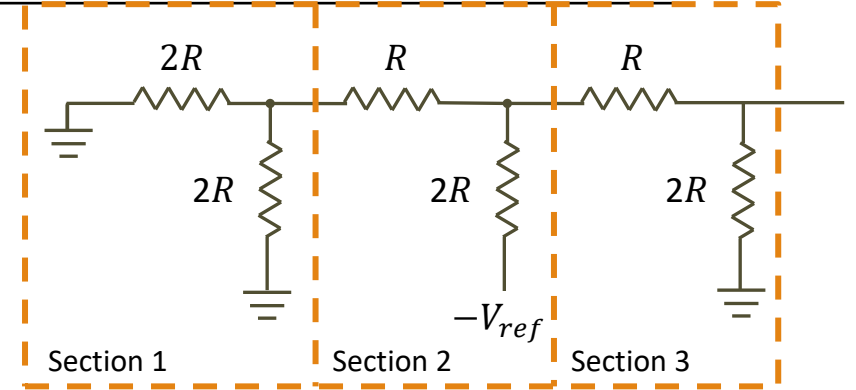
- Let: $b_0 = 0, b_1 = 1, b_2 = 0$
- Section 3:



$$V_{th} = -V_{ref}/4$$

$$R_{th} = R$$

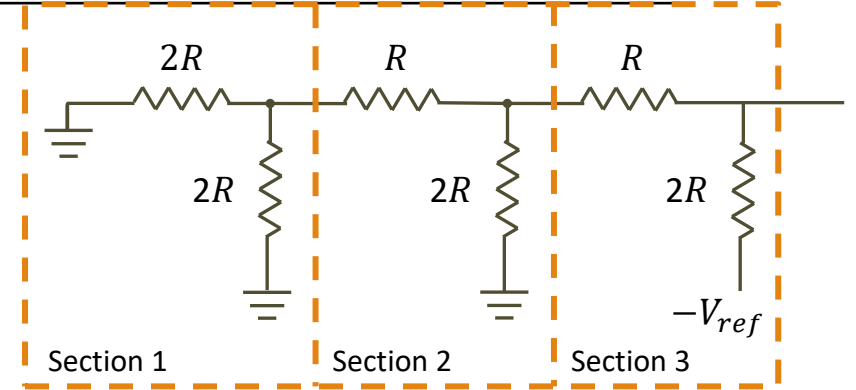
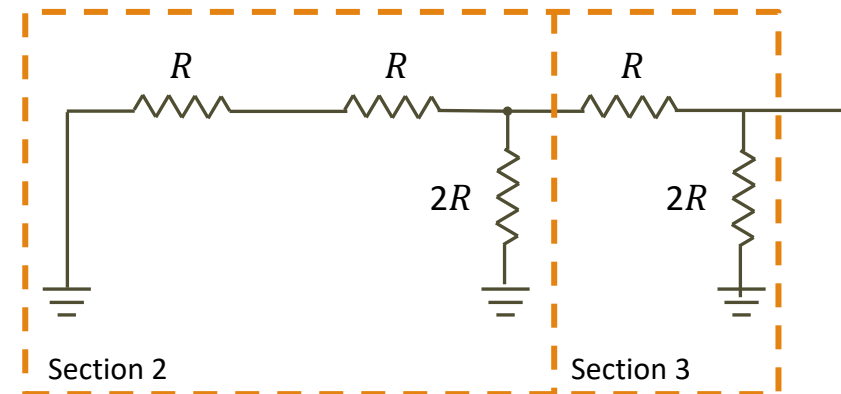
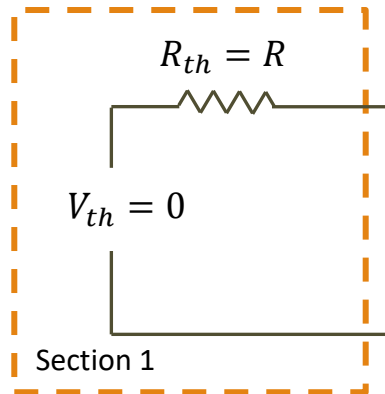
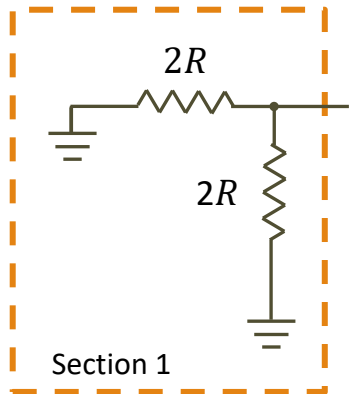
$$V_{out} = - \left(\frac{-V_{ref}}{4} \right) \frac{R_f}{R} \xrightarrow{R_f=R} V_{out} = \frac{V_{ref}}{4}$$



Mechatronics Automation

R-2R ladder DAC:: Circuit analysis for 3 bits

- Let: $b_0 = 0, b_1 = 0, b_2 = 1$
- Section 1:

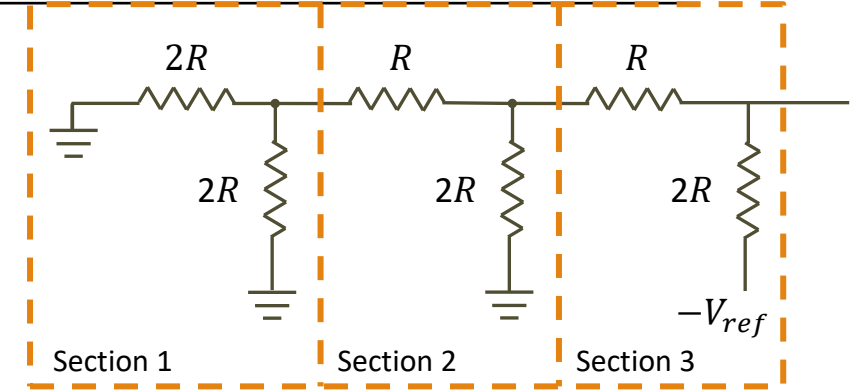
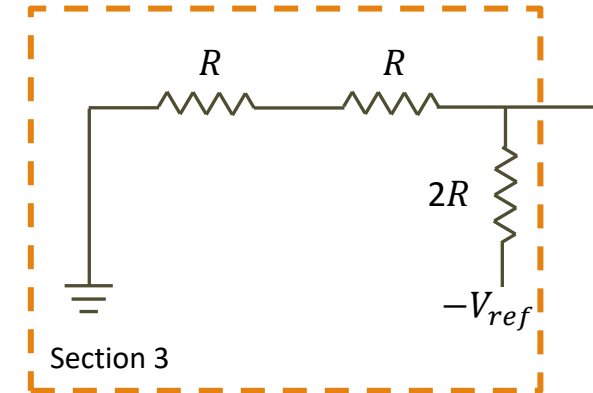
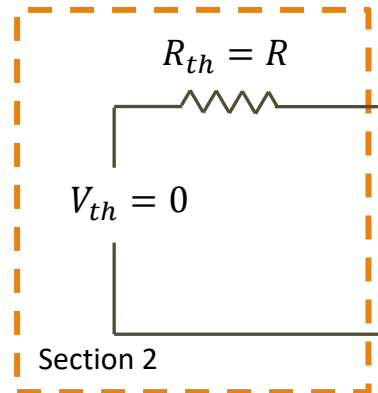
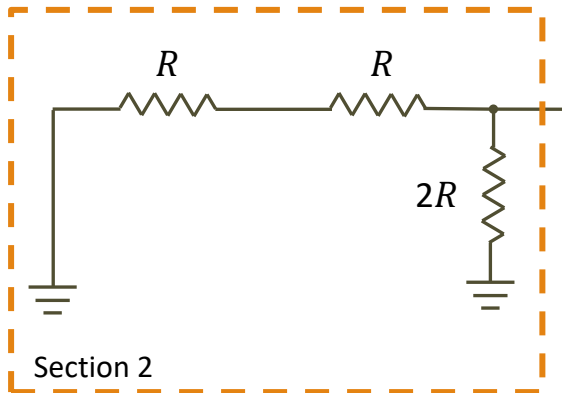


$$V_{th} = 0$$
$$R_{th} = R$$

Mechatronics Automation

R-2R ladder DAC:: Circuit analysis for 3 bits

- Let: $b_0 = 0, b_1 = 0, b_2 = 1$
- Section 2:

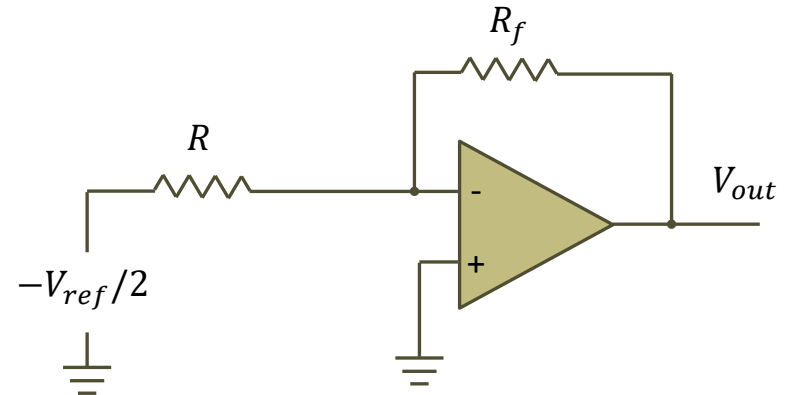
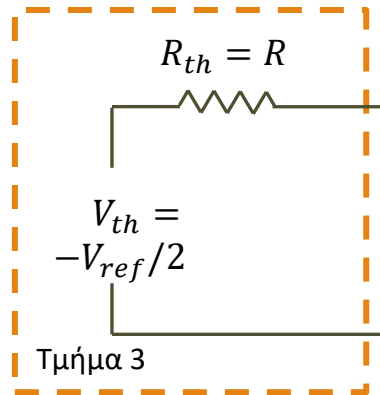
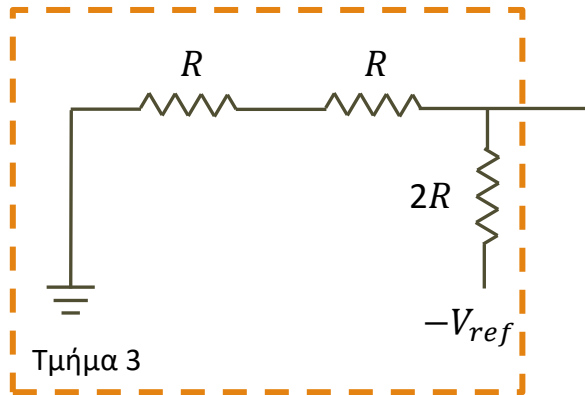


$$V_{th} = 0$$
$$R_{th} = R$$

Mechatronics Automation

R-2R ladder DAC:: Circuit analysis for 3 bits

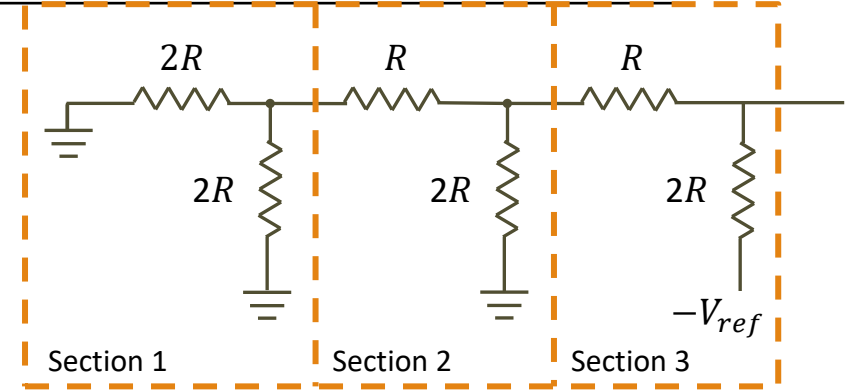
- Let: $b_0 = 0, b_1 = 0, b_2 = 1$
- Section 3:



$$V_{th} = -V_{ref}/2$$

$$R_{th} = R$$

$$V_{out} = -\left(\frac{-V_{ref}}{2}\right) \frac{R_f}{R} \xrightarrow{R_f=R} V_{out} = \frac{V_{ref}}{2}$$



Mechatronics Automation

R-2R ladder DAC:: Circuit analysis for 3 bits

Therefore:

- For: $b_0 = 1, b_1 = 0, b_2 = 0$

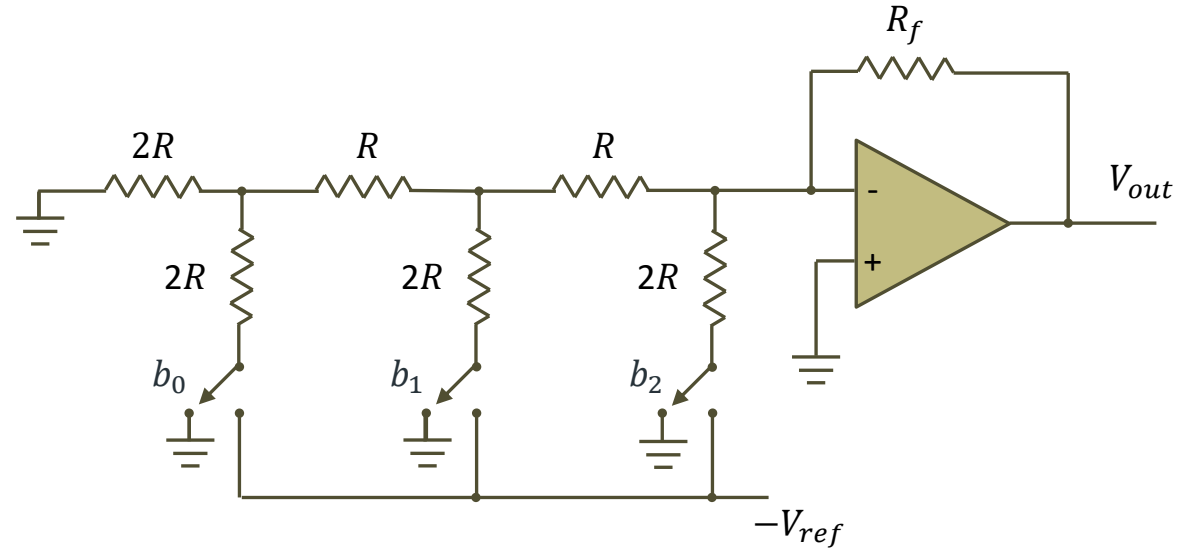
- $V_{out} = \frac{V_{ref}}{8}$

- For: $b_0 = 0, b_1 = 1, b_2 = 0$

- $V_{out} = \frac{V_{ref}}{4}$

- For: $b_0 = 0, b_1 = 0, b_2 = 1$

- $V_{out} = \frac{V_{ref}}{2}$



From the superposition principle and due to the operational amplifier (summing amplifier):

$$V_{out} = b_2 \frac{V_{ref}}{2} + b_1 \frac{V_{ref}}{4} + b_0 \frac{V_{ref}}{8} \Rightarrow V_{out} = V_{ref} \left(\frac{b_2}{2} + \frac{b_1}{4} + \frac{b_0}{8} \right)$$

$$\Rightarrow V_{out} = V_{ref} \left(\frac{b_2}{2^1} + \frac{b_1}{2^2} + \frac{b_0}{2^3} \right)$$