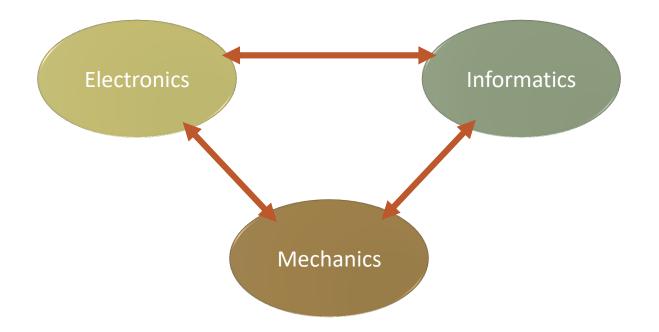
Robust Mechatronics

Fundamentals of Mechatronic Systems

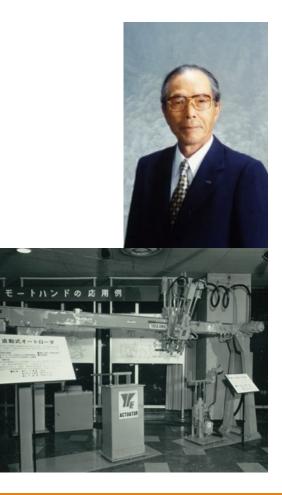


Dr Loukas Bampis, Assistant Professor Mechatronics & Systems Automation Lab

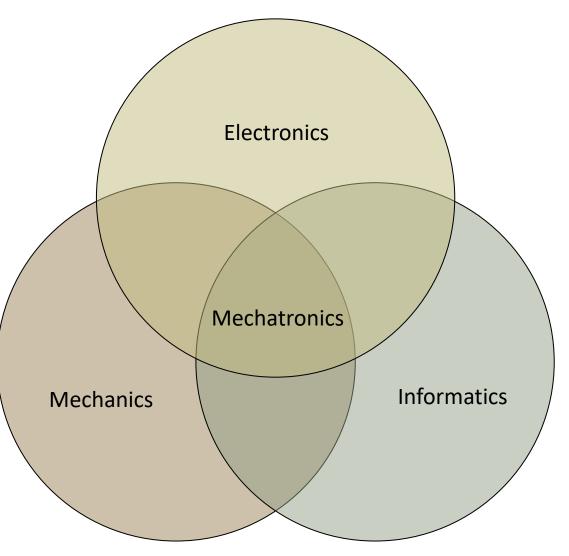
What is Mechatronics?

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Mechanical + Electronics = Mechatronics
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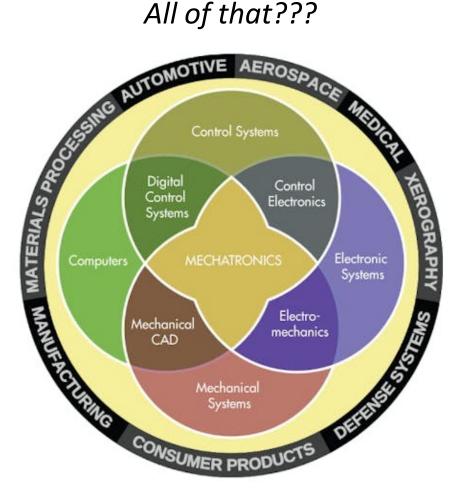
The term was established in 1969 by Tetsuro Mori, senior engineer at the Yaskawa Electric Company, Japan



- Mechatronics is synergistic integration of mechanical engineering, electronics engineering, control engineering and computer science.
- Mechatronics engineering is the design of computercontrolled electromechanical systems.
- A mechatronic system is a computer controlled mechanical system.



- Mechatronics is synergistic integration of mechanical engineering, electronics engineering, control engineering and computer science.
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Source: Wikipedia

Mechatronics component analysis



Our means of interacting with the environment through mechanisms

- Levers
- Mechanical arms
- Wheels
- Gears
- Sprockets chains
- Pulleys belts



Our means of actuating mechanisms and sensing the environment

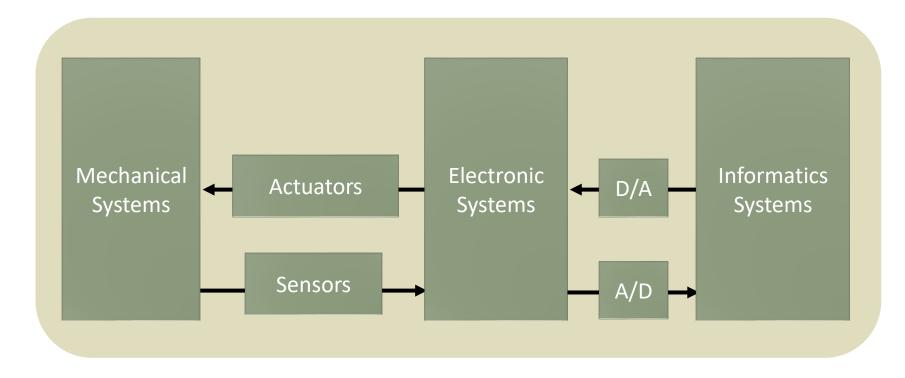
- Resistors
- Capacitors
- Coils
- Transistors
- Operational amplifiers
- Relays
- Actuators
- Microcomputers/microcontrollers



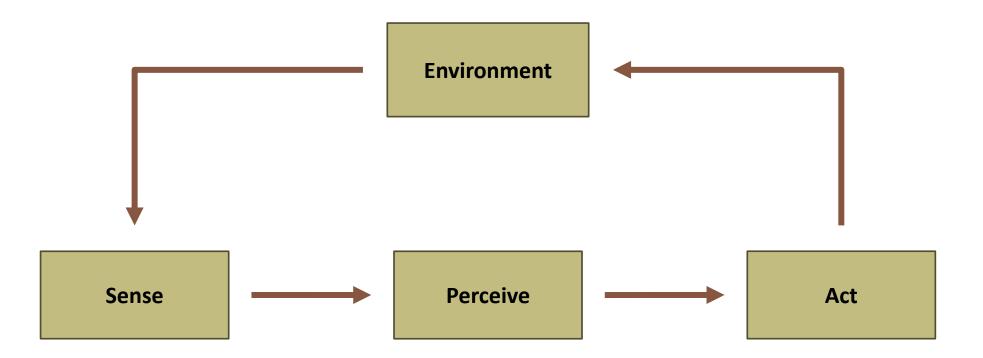
Our means of perceiving and reasoning on sensor inputs and controlling our actions

- Probability theory
- Control
- Estimation theory
- Vision
- Data mining
- Machine learning / Al

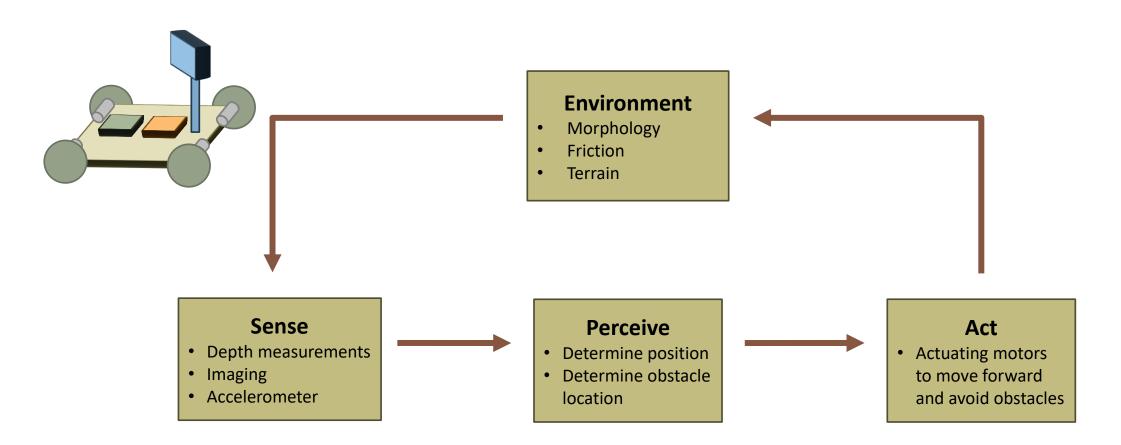
Mechatronics component analysis



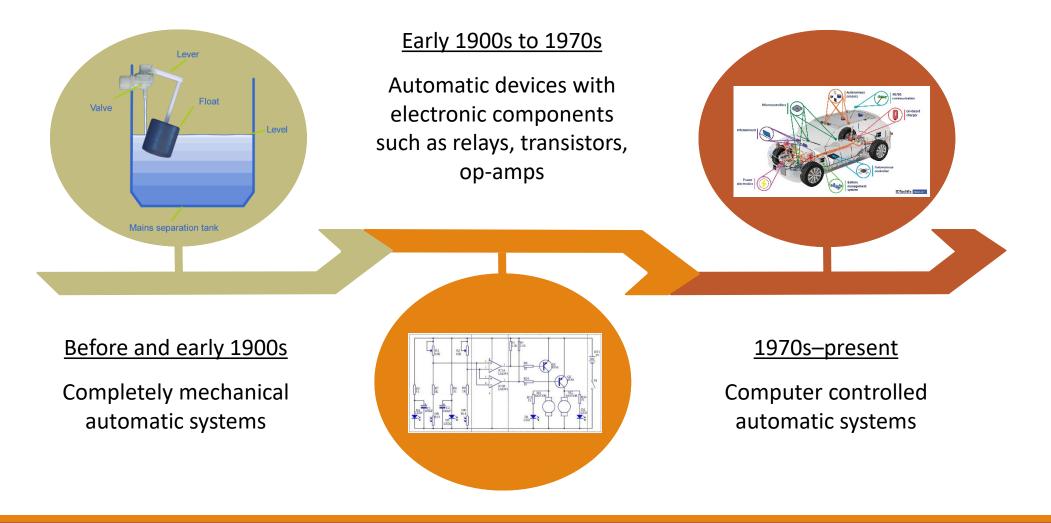
Mechatronics operational analysis

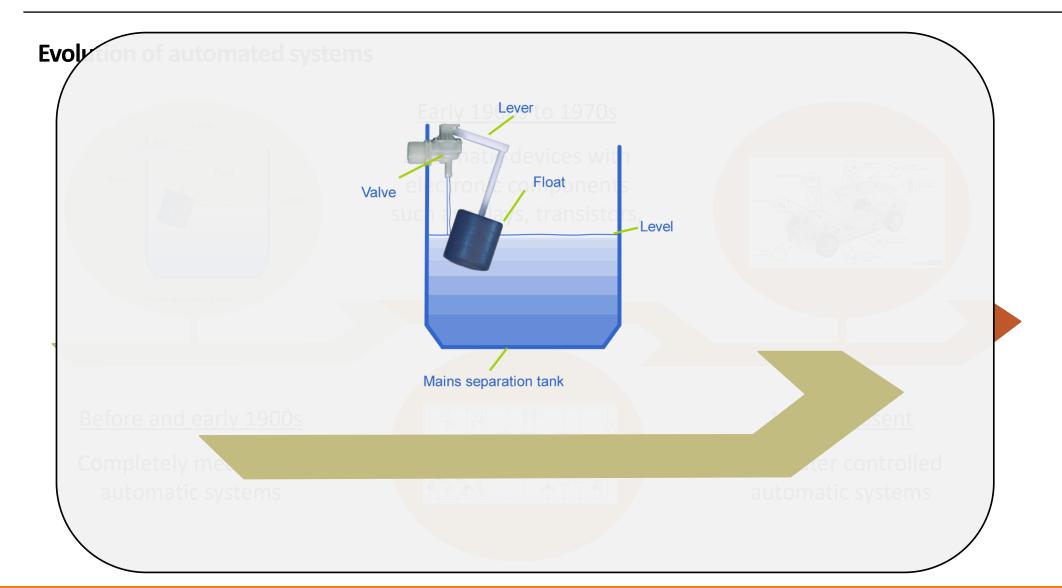


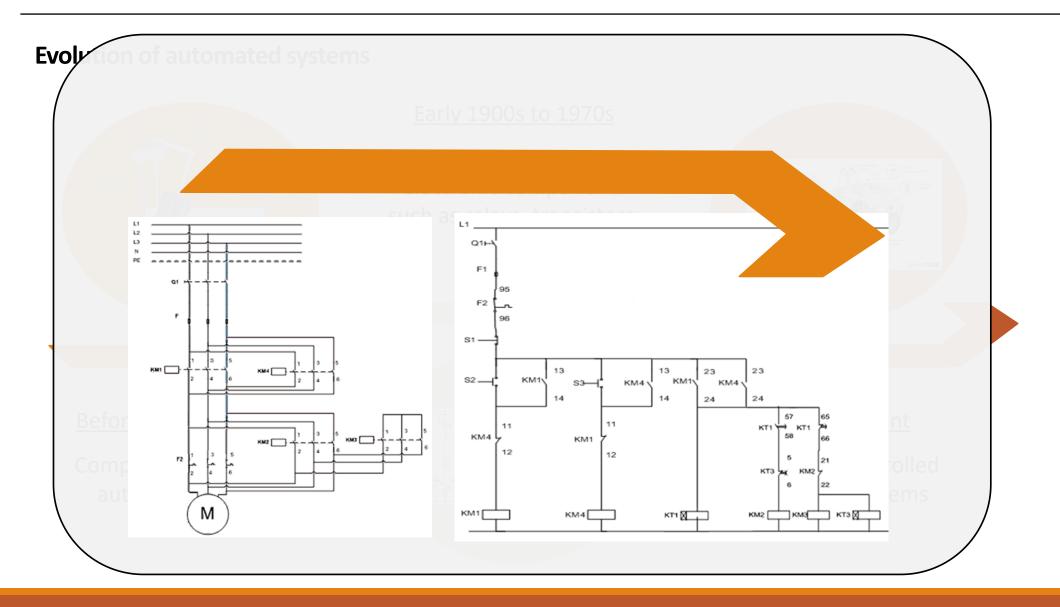


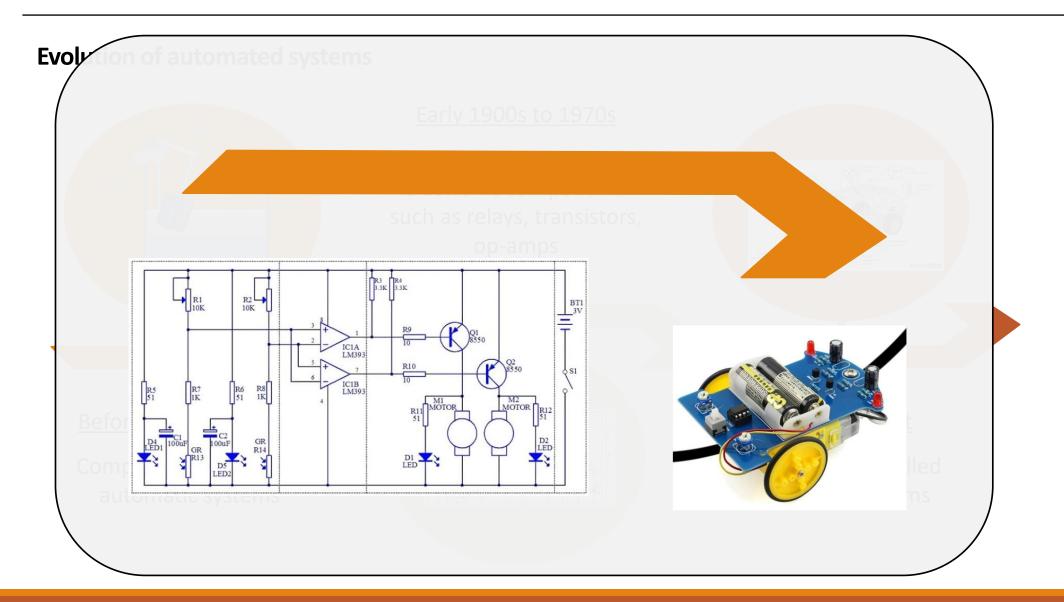


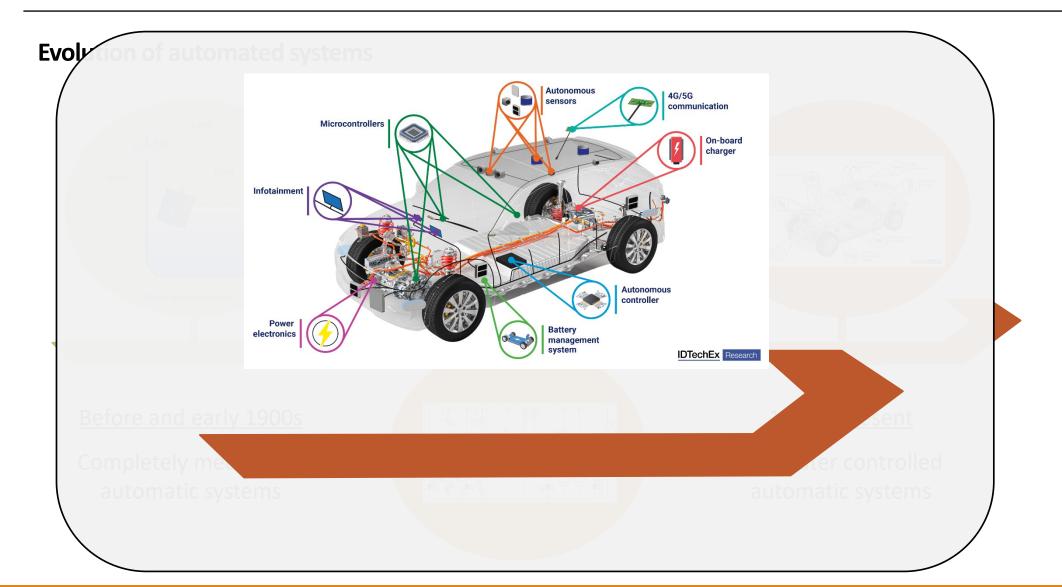
Evolution of automated systems





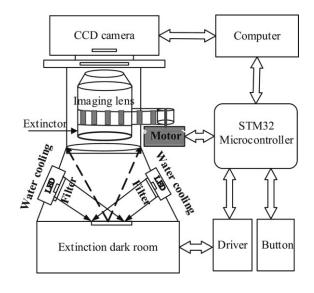


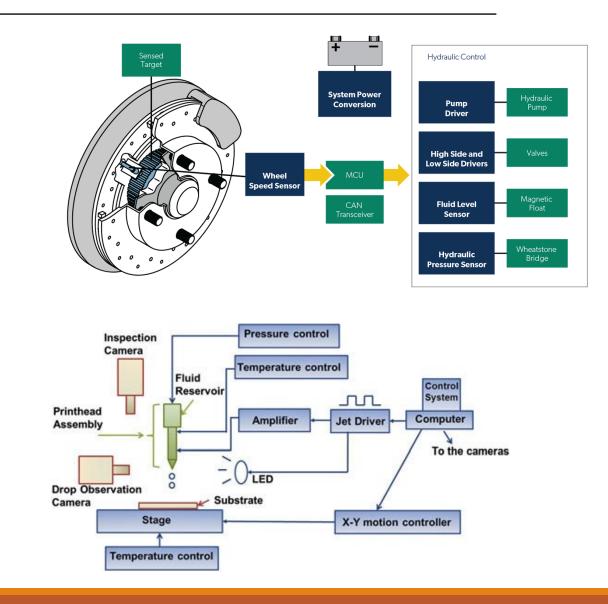




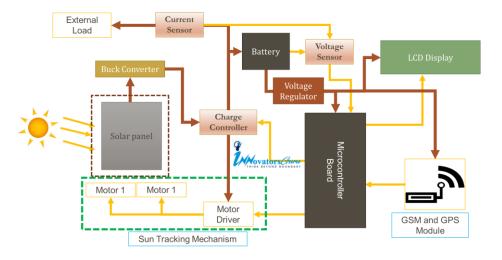
- Antilock Brake System (ABS)
- Scanner
- Printer
- Solar Tracker
- Hard Disk Drive
- Robotic Arms
- Drones / UAVs
- Autonomous Cars
- Mobile Robots (Wheeled Robots, Legged Robots, etc.)
- ...

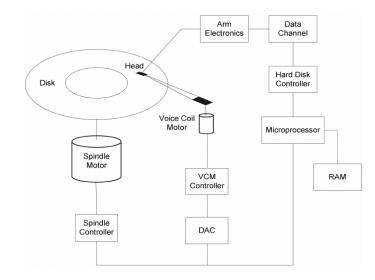
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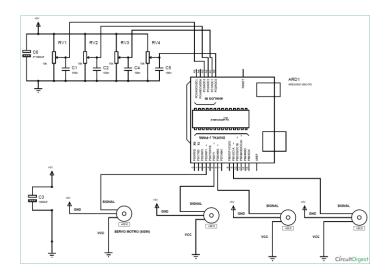




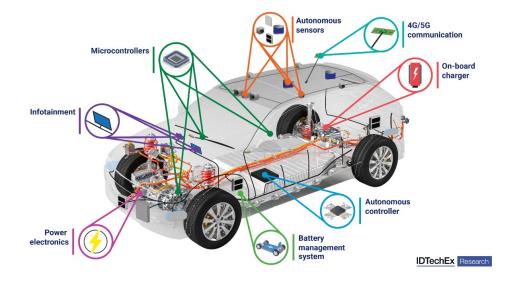
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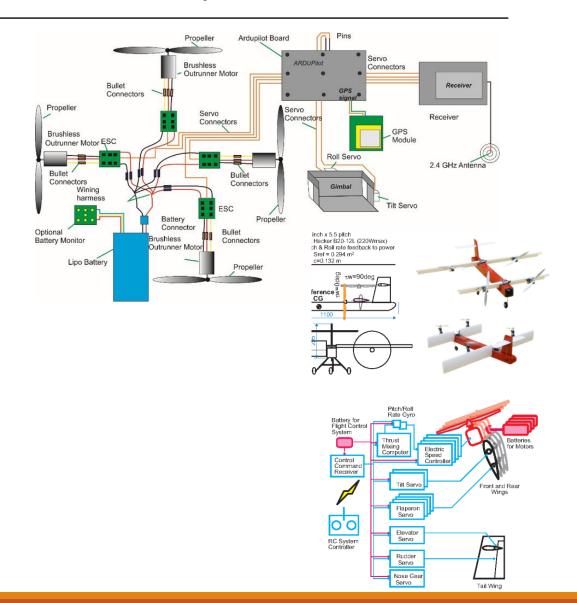






- Drones / UAVs
- Autonomous Cars





Examples of Mechatronic Systems

• Mobile Robots (Wheeled Robots, Legged Robots, etc.)

